Instruction Manual

AZ20.F

Digital LED Display and Control Unit for Panel Mounting,

5 Digits, Frequency Input

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Technical features:

- red display of -19999…99999 digits (optional: green, orange or blue display)
- minimal installation depth: 120 mm without plug-in terminal
- min/max memory
- adjustment via factory default or directly on the sensor signal
- 30 adjustable setpoints
- display flashing at threshold undercut or exceedance
- simplified programming r.p.m. with only 3 parameters
- Schmitt-trigger-input
- zero-key for triggering of Hold, Tara
- permanent min/max-value recording
- digital frequency filter for contact bounce suppression and interference suppresion
- frequency filter with varying pulse-duty factor
- volume metering (totaliser) for frequencies up to 1 kHz (accurate to a pulse)
- mathematical function like reciprocal value, square root, rounding
- sliding averaging with an optional dynamic display filter
- setpoint generator
- brightness control
- programming interlock via access code
- protection class IP65 at the front
- plug-in terminal
- sensor supply
- galv. isolated digital input
- option: 2 or 4 relay outputs or 8 PhotoMos outputs
- option: 1 or 2 analog outputs
- option: interface RS232 or RS485
- accessories: PC-based configuration-kit PM-TOOL incl. CD & USB-adapter for devices without keypad and for a simple adjustment of standard devices

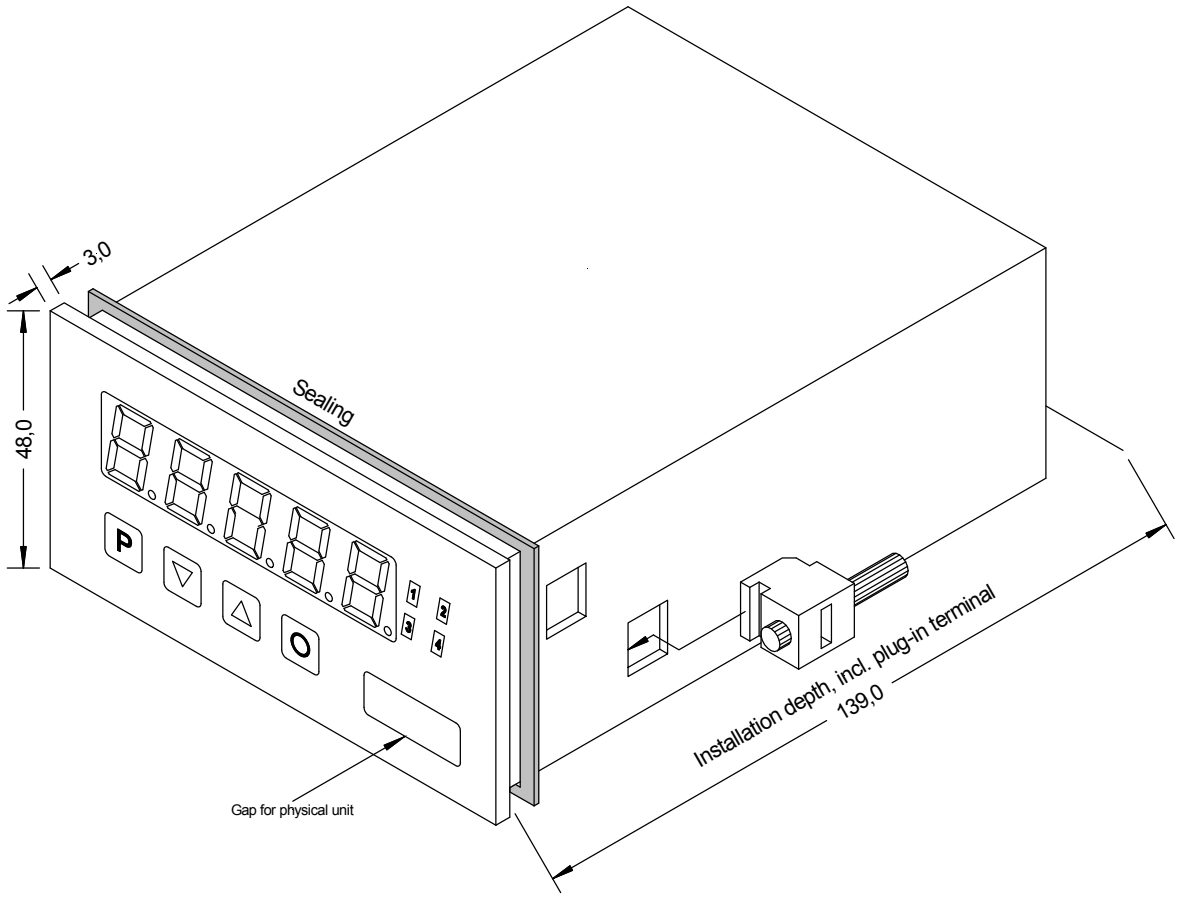
Contents

1. Brief description

The panel meter AZ20.F evaluates pulses in many different ways and shows the result in the 5-digit LED-display. Available options are: frequency coverage with optional filters, summate of pulses or display values via time, detection of a rotational speed or collection of a position via an incremental encoder. The results can be monitored via alarm conditions and can be displayed onto the optional switching point. Furthermore the results can be freely scaled on an optional analog output and relayed to a control system. The device can be operated directly by Namur sensors, 3-wire sensors, switching/slider contacts, incremental encoders (HTL-/TTL-output) or TTL-signals.
Via the 4 navigation keys on the front, the device can be adjusted onto different kind of applications and later on different functions of the device can be controlled. The adjustment is also possible via the PC-Software PM-TOOL with a special connecting cable. With an individual code, the created parameterisation can be protected against changes of the user.
Numerous applications can be realised with this device, like e.g. tachometer, revolution counter, flowmeter, dosing equipment, filling capacity meter, baking time meter of a baking oven, flying knife, position evaluation, position surveillance, flow rate surveillance, acoustic discharge measurements and so on. By use of the integrated, configurable functions like permanent min/max-recording, averaging, frequency filter, setpoint setting, threshold value recording via alarm system, 30-points-linearisation, mathematic charging and many more, you receive an universal applicable modern system for your demands in measuring and control technique.

2. Assembly

Please read the *Safety advices* on *page 39* before installation and keep the user manual for future reference.



1. After removing the fixing elements, insert the device.
2. Check the seal to make sure it fits securely.
3. Click the fixing elements back into place and tighten the clamping screws by hand. Then use a screwdriver to tighten them another half a turn.

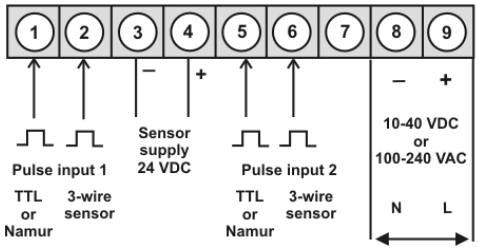
CAUTION! The torque should not exceed 0.1 Nm!

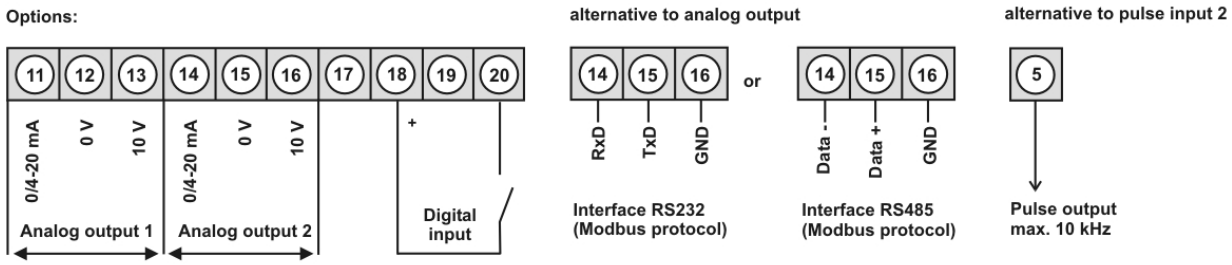
The dimension symbols can be exchanged before installation via a channel on the side!

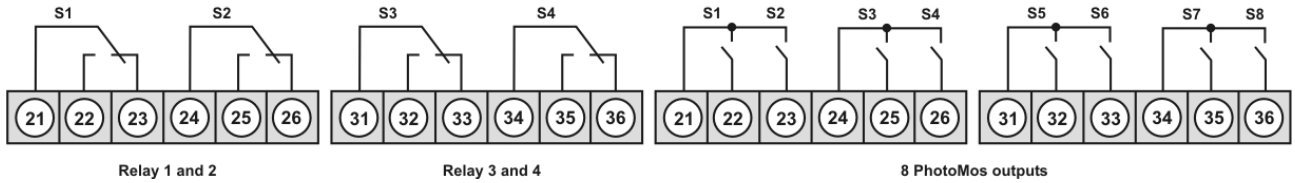
3. Electrical connection

Type AZ20.F.1... supply 100-240 VAC, DC ± 10%

Type AZ20.F.2... supply 10-40 VDC, galv. isolated, 18-30 VAC





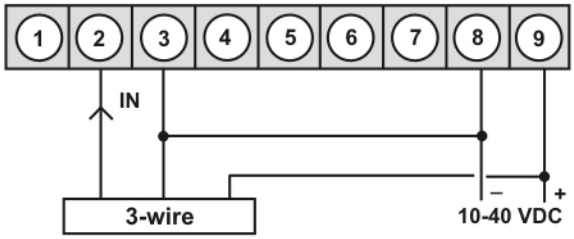


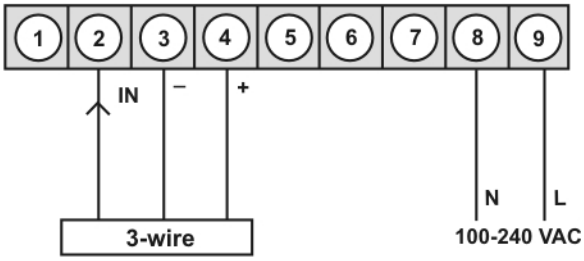
Advice:

If Namur sensors with a nominal voltage of approx. 8 V are used, then a sensor supply of 12 VDC is needed. For devices with a sensor supply terminals 4 and 18, aswell as terminals 3 and 19 need to be galvanically connected in the device.

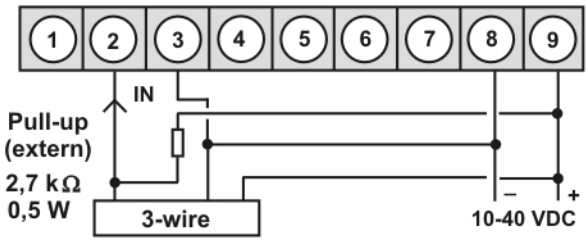
Connection examples

Below you find some connection examples with practical applications:

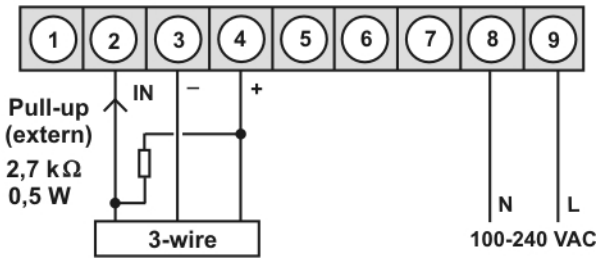




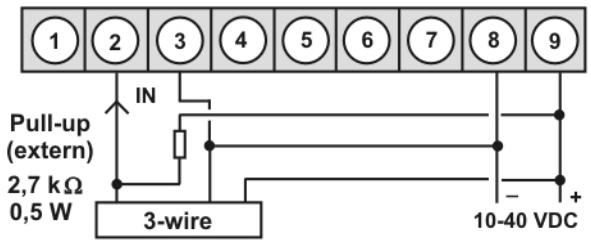
3-wire NPN



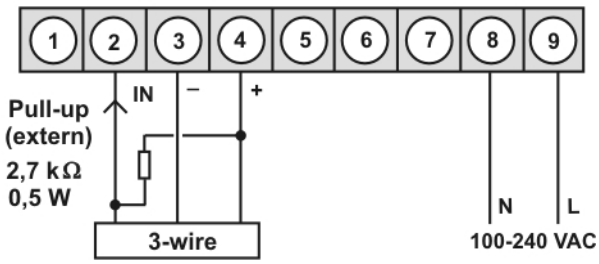
3-wire NPN



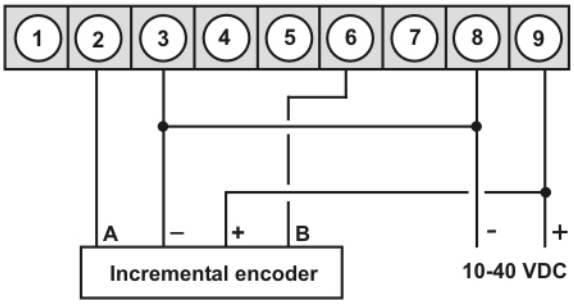
3-wire NPN



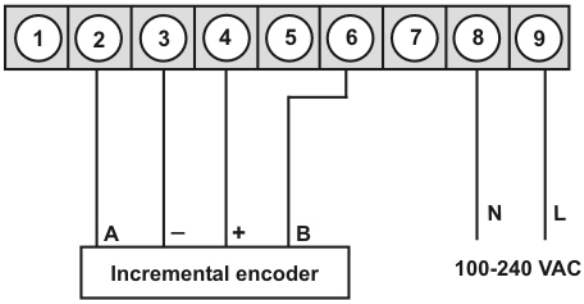
3-wire NPN



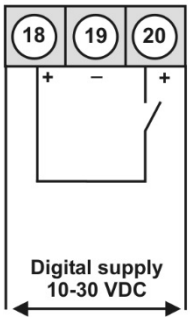
Incremental encoder



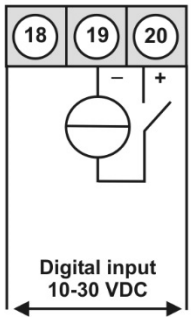
Incremental encoder (max. 50 mA current consumption)



M3 with digital input in combination with 24 VDC sensor supply



M3 with digital input and external voltage source



4. Function and operation description

Operation
The operation is divided into three different levels.

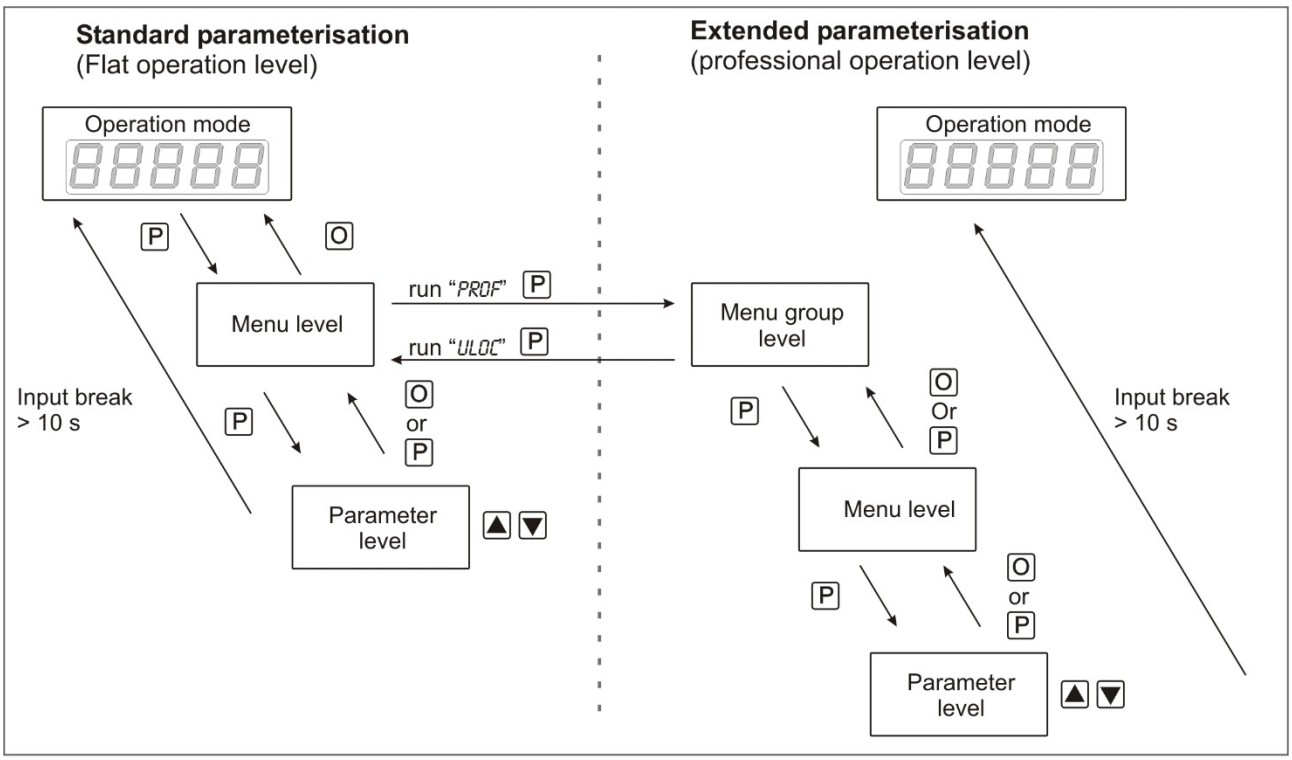
Menu level (delivery status)
This level was designed for the standard settings of the device. Only menu items which are sufficent to set the device into operation are displayed. To get into the professional level, run through the menu level and parameterise *PROF* under menu item *RUN*.

Menu group level (complete function volume)
Suited for complex applications as e.g. linkage of alarms, setpoint treatment, totaliser function etc. In this level function groups which allow an extended parameterisation of the standard settings are availabe. To leave the menu group level, run through this level and parameterise *ULOC* under menu item *RUN*.

Parameterisation level:
Parameter deposited in the menu item can be parameterised here. Functions, that can be changed or adjusted, are always signalised by a flashing of the display. Settings that are made in the parameterisation level are confirmed with **[P]** and thus saved. Pressing the **[O]-key** („zero-key“) leads to a break-off of the value input and to a change into the menu level. All adjustments are saved automatically by the device and changes into operating mode, if no further key operation is done within the next 10 seconds.

Level	Key	Description
Menu level	P	Change to parameterisation level and deposited values.
	▲ ▼	Keys for up and down navigation in the menu level.
	O	Change into operation mode.
Parameterisation level	P	To confirm the changes made at the parameterization level.
	▲ ▼	Adjustment of the value / the setting.
	O	Change into menu level or break-off in value input.
Menu group level	P	Change to menu level.
	▲ ▼	Keys for up and down navigation in the menu group level.
	O	Change into operation mode or back into menu level.

Function chart:



Underline:

P	**Takeover**	▲	**Value selection (+)**
O	**Stop**	▼	**Value selection (-)**

4.1. Parameterisation software PM-TOOL:

Included in the delivery of the PM-TOOL are the software on CD and an USB-cable with device adapter. The connection happens via a 6-pole micromatch-plug on the back side of the device, to the PC-side the connection happens via an USB plug.

System requirements: PC incl. USB interface
Software: Windows XP, Windows VISTA

With this tool the device configuration can be generated, omitted and saved on the PC. The parameters can be changed via the easy to handle program surface, whereat the operating mode and the possible selection options can be preset by the program.

5. Setting up the device

5.1. Switching-on

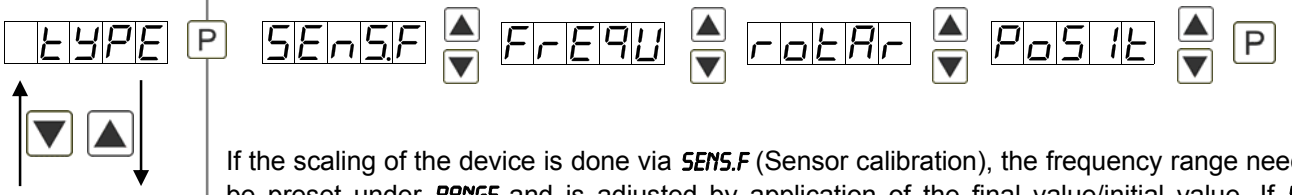
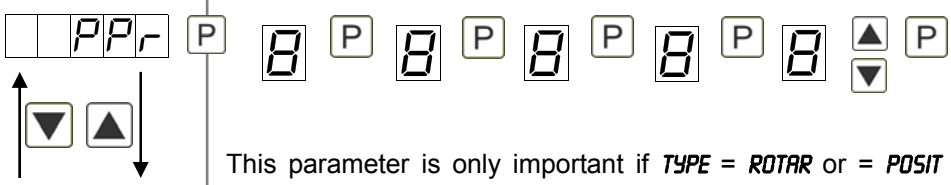
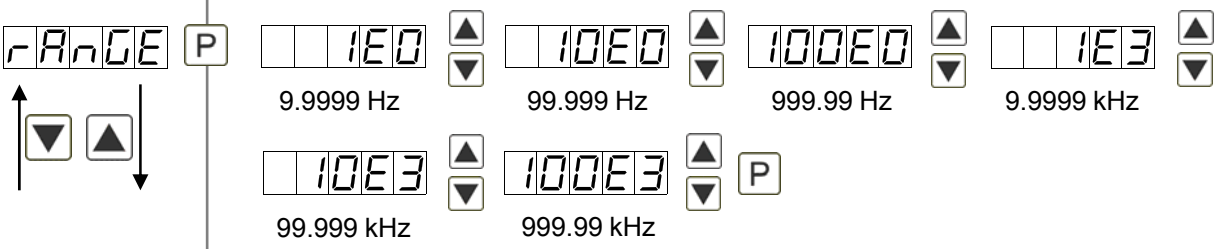
Once the installation is complete, start the device by applying the voltage supply. Before, check once again that all electrical connections are correct.

Starting sequence

For 1 second during the switching-on process, the segment test (8 8 8 8 8) is displayed, followed by an indication of the software type and, after that, also for 1 second, the software version. After the starting sequence, the device switches to operation/display mode.

5.2. Standard parameterisation: (flat operation level)

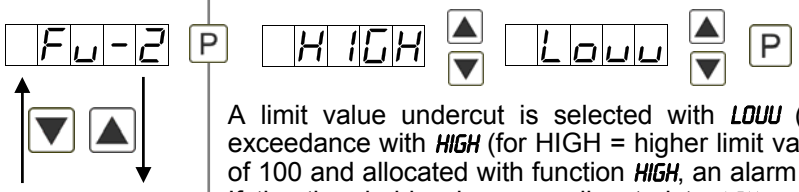
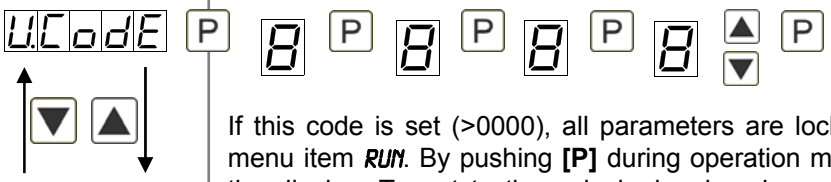
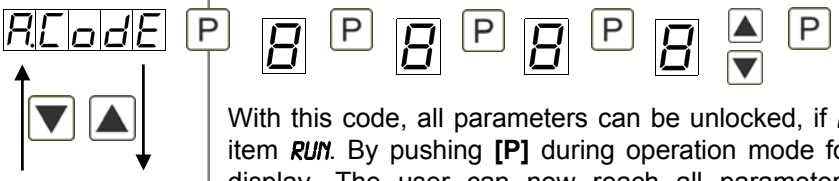
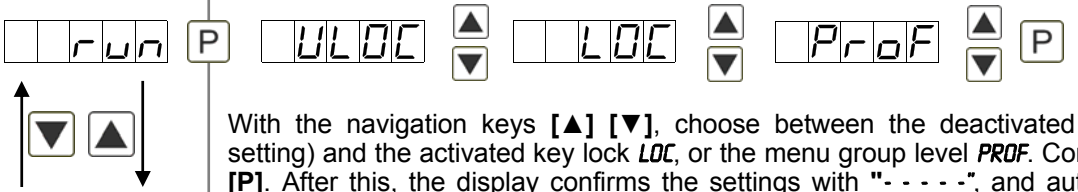
To parameterize the display, press the **[P]-key** in operating mode for 1 second. The display then changes to the menu level with the first menu item TYPE.

Menu level	Parameterisation level
	**Selection of the input signal, TYPE:** Default: FREQU If the scaling of the device is done via SENS.F (Sensor calibration), the frequency range needs to be preset under RANGE and is adjusted by application of the final value/initial value. If FREQU (Factory calibration) is preferred, the final value needs to be entered under END and the final frequency needs to be entered under ENDA. Under OFFS the initial value needs to be entered and under OFFSA the initial frequency. There is no application of the measuring signal. ROTAR is the rotation in r.p.m. up to 10 kHz input frequency. POSIT is the position recognition per incremental encoder. Confirm the selection with **[P]** and the display switches back to menu level.
	**Adjustment of pulses per rotation, PPR:** Default: 1 This parameter is only important if TYPE = ROTAR or = POSIT have been selected. Generally it shows the number of pulses per rotation.
	**Setting the frequency range, RANGE:** Default: 100E3 Choose between six different frequency ranges. Confirm the selection with **[P]** and the display switches back to menu level.

Menu level	Parameterisation level
End	**Setting the upper range value, END:** Default: 10000 End P 8 P 8 P 8 P 8 P 8 ▲ ▼ | nOCA ▲ P CAL ▼ Set the final value from the smallest to the highest digit with **[▲] [▼]** and confirm each digit with **[P]**. A minus sign can only be parameterized on the leftmost digit. After the last digit, the display switches back to the menu level. If SENS was selected as input option, one can only select between NOCA and CAL. With NOCA, only the previously set display value is taken over, and with CAL, the device takes over both the display value and the analogue input value.
OFFS	**Setting the lower range value, OFFS:** Default: 0 OFFS P 8 P 8 P 8 P 8 P 8 ▲ ▼ | nOCA ▲ P CAL ▼ Enter the start/offset value from the smallest to the highest digit **[▲] [▼]** and confirm each digit with **[P]**. After the last digit the display switches back to the menu level. If SENS.F was selected as the input option, one can only select between NOCA and CAL. With NOCA, only the previously set display value is taken over, and with CAL, the device takes over both the display value and the analogue input value.
dot	**Setting the comma/decimal point, DOT:** Default: 0 dot P 0 ▲ ▼ 0.0 ▲ ▼ 0.00 ▲ ▼ 0.000 ▲ ▼ 0.0000 ▲ ▼ P The decimal point on the display can be moved with **[▲] [▼]** and confirmed with **[P]**. The display then switches back to the menu level again.
SEC	**Setting up the display time, SEC:** Default: 1.0 SEC P 00.1 ▲ ▼ 00.9 then 01.0 ▲ ▼ 10.0 ▲ ▼ P The display time is set with **[▲] [▼]**. The display moves up in increments of 0.1 up to 1 second and in increments of 1.0 up to 10.0 second. Confirm the selection by pressing the **[P]** button. The display then switches back to the menu level again.
EndA	**Rescale the input frequency, ENDA:** Default: 10000 EndA P 8 P 8 P 8 P 8 P 8 ▲ ▼ P With this function, one can rescale the input value of **e.g. 8.000 Hz** (works setting) without applying a measuring signal. If sensor calibration has been selected, these parameters are not available.

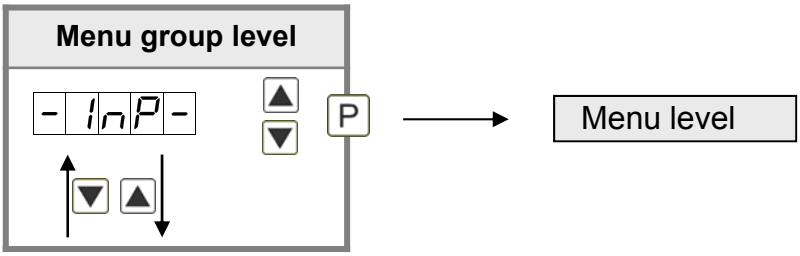
Menu level	Parameterisation level
OFFSA	**Rescale the input frequency, OFFSA:** Default: 0 OFFSA P 8 P 8 P 8 P 8 P 8 ▲▼ P With this function, rescale the input value of **e.g. 100 Hz** (works setting) without applying a measuring signal. If sensor calibration has been selected, these parameters are not available.
dELAY	**Setting of the pulse delay, DELAY:** Default: 0 dELAY P 0 ▲▼ 250 ▲▼ P With the pulse delay of 0–250 seconds (maximum), frequencies can be collected, which are even smaller than by the predetermined measuring time of the device. If e.g. a delay of 250 seconds is set, this means that the device waits up to 250 seconds for an edge, before it assumes a 0 Hz frequency. Thus frequencies up to 0.004Hz can be collected.
FI.Fr9	**Adjustment of the optimum digital frequency filter, FI.FRQ:** Default: NO FI.Fr9 P no ▲▼ 100 ▲▼ 50 ▲▼ 20 ▲▼ 10 ▲▼ 5 ▲▼ 2 ▲▼ P If the optional filter is not activated by the adjustment NO, frequencies are ignored by the adjusted frequency filter. Act on the assumption that the pulse-duty factor is 1:1. Accordingly the minimal pulse duration is derived from half of the time of oscillation. Use a filter of 10Hz or 20Hz for contact bounce suppression.
OutrA	**Selection of analog output, OUT.RA:** Default: 4-20 OutrA P 0-10 ▲▼ 0-20 ▲▼ 4-20 ▲▼ P Three output signals are available: 0-10 VDC, 0-20 mA and 4-20 mA, with this function, the demanded signal is selected.
OutEn	**Setting the upper value of the analog output, OUT.EN:** Default: 10000 OutEn P 8 P 8 P 8 P 8 P 8 ▲▼ P The final value is adjusted from the smallest digit to the highest digit with **[▲] [▼]** and digit by digit confirmed with **[P]**. A minus sign can only be parameterised on the highest digit. After the last digit, the device changes back into menu level.

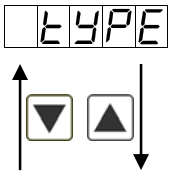
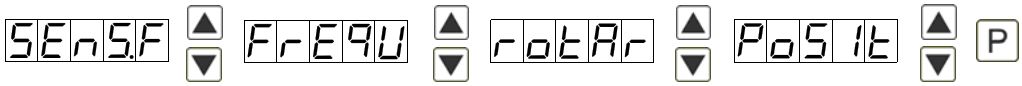
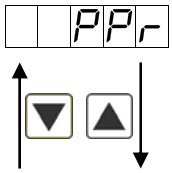
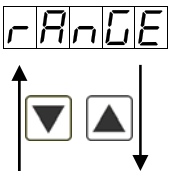
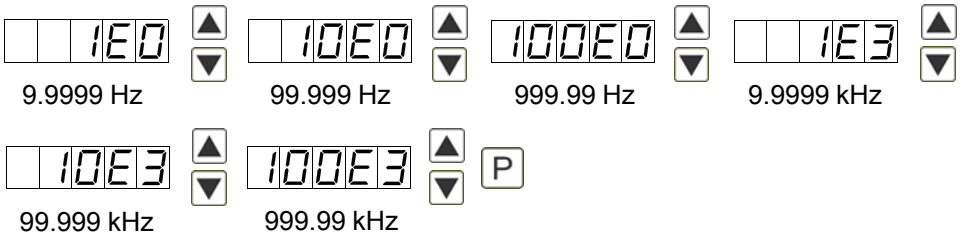
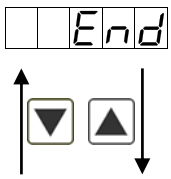
Menu level	Parameterisation level
OUT.OF	**Setting the lower value of the analog output, OUT.OF:** Default: 00000 The final value is adjusted from the smallest digit to the highest digit with **[▲] [▼]** and digit by digit confirmed with **[P]**. A minus sign can only be parameterised on the highest digit. After the last digit, the device changes back into menu level.
L1-1	**Threshold values / limit values, LI-1:** Default: 2000 For both limit values, two different values can be parameterized. With this, the parameters for each limit value are called up one after another.
HY-1	**Hysteresis for limit values, HY-1:** Default: 00000 For all limit values exists a hysteresis function, that reacts according to the settings (threshold exceedance / threshold undercut).
FU-1	**Function for threshold value exceedance/undercut, FU-1:** Default: HIGH The limit value undercut can be selected with LOUU (LOW = lower limit value) and limit value exceedance can be selected with HIGH (HIGH = upper limit value). If e.g. limit value 1 is on a switching threshold of 100 and occupied with function HIGH, the alarm will be activated by reaching the threshold. If the limit value is allocated to LOW, an alarm will be activated by undercut of the threshold. See page 29.
L1-2	**Threshold values / limit values, LI-2:** Default: 3000 This value defines the threshold, that activates/deactivates an alarm.
HY-2	**Hysteresis for limit values, HY-2:** Default: 00000 The delayed reaction of the alarm is the difference to the threshold value, which is defined by the hysteresis.

Menu level	Parameterisation level
	**Function for threshold value exceedance/undercut, FU-2:** Default: HIGH A limit value undercut is selected with LOUU (for LOW = lower limit value), a limit value exceedance with HIGH (for HIGH = higher limit value). If e.g. limit value 1 is on a threshold level of 100 and allocated with function HIGH, an alarm is activated by reaching of the threshold level. If the threshold value was allocated to LOW, an alarm will be activated by undercutting the threshold value, as long as the hysteresis is zero.
	**User code (4-digit number-combination, free available), U.CODE:** Default: 0000 If this code is set (>0000), all parameters are locked, if LOC has been selected before under menu item RUN. By pushing **[P]** during operation mode for approx. 3 seconds, CODE appears in the display. To get to the unlocked reduced parameter, the user needs to enter the preset U.CODE. This code has to be entered before each parameterisation, until the A.CODE (master code) unlocks all parameters again.
	**Master code (4-digit number-combination free available), A.CODE:** Default: 1234 With this code, all parameters can be unlocked, if LOC has been activated before under menu item RUN. By pushing **[P]** during operation mode for approx. 3 seconds, CODE appears in the display. The user can now reach all parameters by entering A.CODE. Leaving the parameterisation, under menu item RUN, the user can release them permanently by choosing ULOC or PROF. So, there is no need for anew code entering, even by pushing **[P]** during operation mode again.
5.3. Programming interlock „RUN“	
	**Activation / deactivation of the programming lock or completion of the standard parameterization with change into menu group level (complete function range), RUN:** Default: ULOC With the navigation keys **[▲] [▼]**, choose between the deactivated key lock ULOC (works setting) and the activated key lock LOC, or the menu group level PROF. Confirm the selection with **[P]**. After this, the display confirms the settings with **"- - - - -"**, and automatically switches to operating mode. If LOC was selected, the keyboard is locked. To get back into the menu level, press **[P]** for 3 seconds in operating mode. Now enter the CODE (works setting 1 2 3 4) that appears using **[▲] [▼]** plus **[P]** to unlock the keyboard. FAIL appears if the input is wrong. To parameterise further functions PROF needs to be set. The device confirms this setting with „- - - - -„ and changes automatically into operation mode. By pressing **[P]** for approx. 3 seconds in operation mode, the first menu group INP is shown in the display and thus confirms the change into the extended parameterisation. It stays activated as long as ULOC is entered in menu group RUN , thus the display is set back in standard parameterisation again.

5.4. Extended parametrisation (Professional operation level)

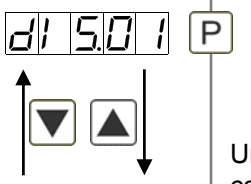
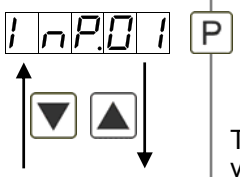
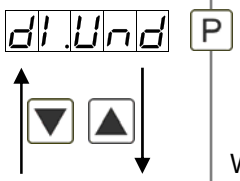
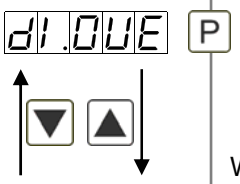
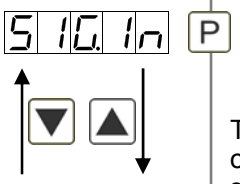
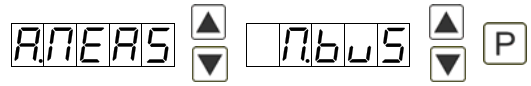
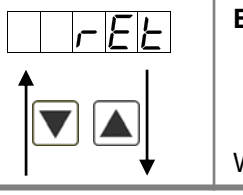
5.4.1. Signal input parameters



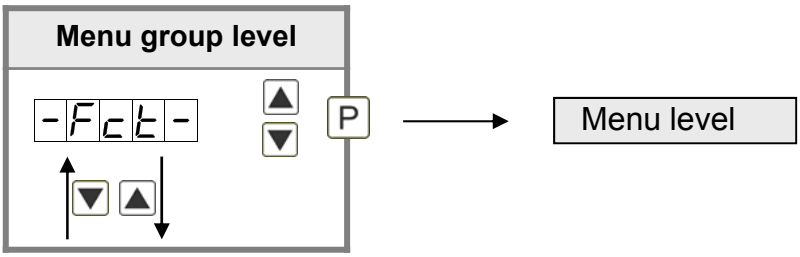
Menu level	Parameterisation level
	**Selection of the input signal, *TYPE*:** Default: *FREQU*  If the scaling of the device is done via *SENS.F* (Sensor calibration), the frequency range needs to be preset under *RANGE* and is adjusted by application of the final value/initial value. If *FREQU* (Factory calibration) is preferred, the final value needs to be entered under *END* and the final frequency needs to be entered under *ENDA*. Under *OFFS* the initial value needs to be entered and under *OFFSA* the initial frequency. There is no application of the measuring signal. *ROTAR* is the rotation in r.p.m. up to 10 kHz input frequency. *POSIT* is the position recognition per incremental encoder. Confirm the selection with **[P]** and the display switches back to menu level.
	**Adjustment of pulses per rotation, *PPR*:** Default: *1*  This parameter is only important if *TYPE* = *ROTAR* or = *POSIT* have been selected. Generally it shows the number of pulses per rotation.
	**Setting the frequency range, *RANGE*:** Default: *100E3*  9.9999 Hz 99.999 Hz 999.99 Hz 9.9999 kHz 99.999 kHz 999.99 kHz Choose between six different frequency ranges. Confirm the selection with **[P]** and the display switches back to menu level.
	**Setting the upper range value, *END*:** Default: *10000*  Set the final value from the smallest to the largest digit with **[▲] [▼]** and confirm each digit with **[P]**. A minus sign can only be parameterized on the leftmost digit. After the last digit, the display switches back to the menu level. If *SENS* was selected as input option, one can only select between *NOCA* and *CAL*. With *NOCA*, only the previously set display value is taken over, and with *CAL*, the device takes over both the display value and the analogue input value.

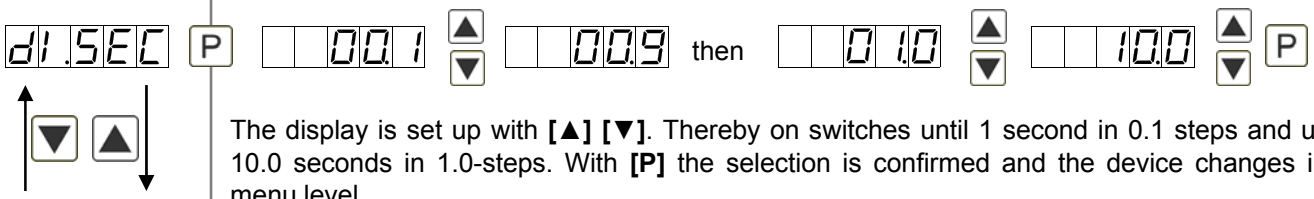
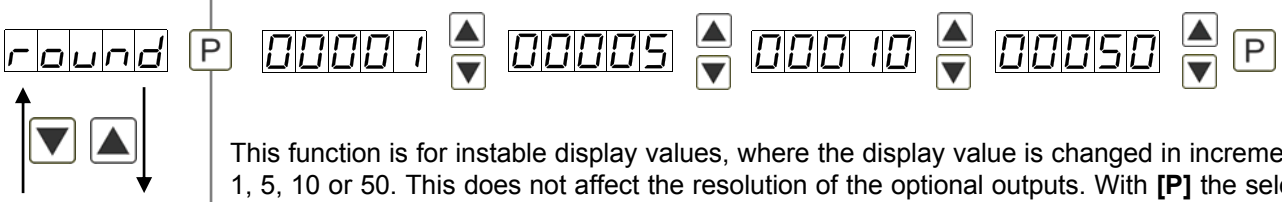
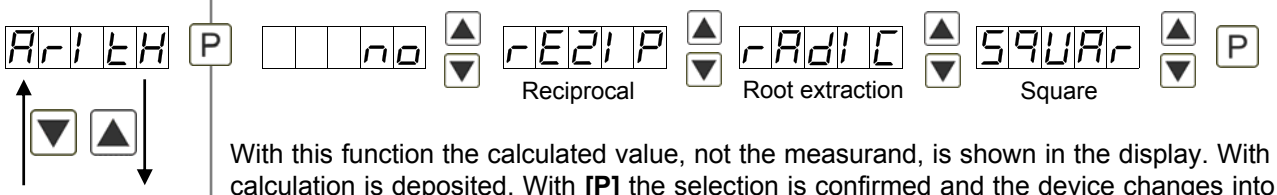
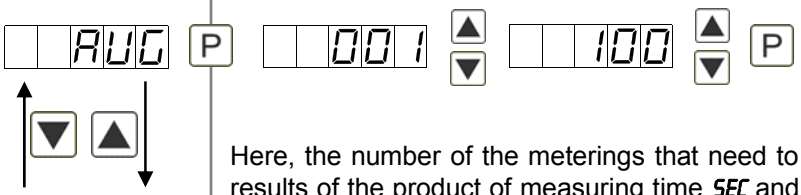
Menu level	Parameterisation level
OFFS	**Setting the lower range value, OFFS:** Default: 0 OFFS P 8 P 8 P 8 P 8 P 8 ▲▼ | nOCA CAL ▲▼ P Enter the start/offset value from the smallest to the highest digit **[▲] [▼]** and confirm each digit with **[P]**. After the last digit the display switches back to the menu level. If SENS.F was selected as the input option, one can only select between NOCA and CAL. With NOCA, only the previously set display value is taken over, and with CAL, the device takes over both the display value and the analogue input value.
dot	**Setting the comma/decimal point, DOT:** Default: 0 dot P 0 ▲▼ 0.0 ▲▼ 0.00 ▲▼ 0.000 ▲▼ 0.0000 ▲▼ P The decimal point on the display can be moved with **[▲] [▼]** and confirmed with **[P]**. The display then switches back to the menu level again.
SEC	**Setting up the display time, SEC:** Default: 1.0 SEC P 00.1 ▲▼ 00.9 then 01.0 ▲▼ 10.0 ▲▼ P The display time is set with **[▲] [▼]**. The display moves up in increments of 0.1 up to 1 second and in increments of 1.0 up to 10.0 seconds. Confirm the selection by pressing the **[P]** button. The display then switches back to the menu level again.
EndA	**Rescale the input frequency, ENDA:** Default: 10000 EndA P 8 P 8 P 8 P 8 P 8 ▲▼ P With this function, rescale the input value of **e.g. 8.000 Hz** (works setting) without applying a measuring signal. If sensor calibration has been selected, these parameters are not available.
OFFSA	**Rescaling the input frequency, OFFA:** Default: 0 OFFSA P 8 P 8 P 8 P 8 P 8 ▲▼ P With this function, rescale the input value of **e.g. 100 Hz** (works setting) without applying a measuring signal.

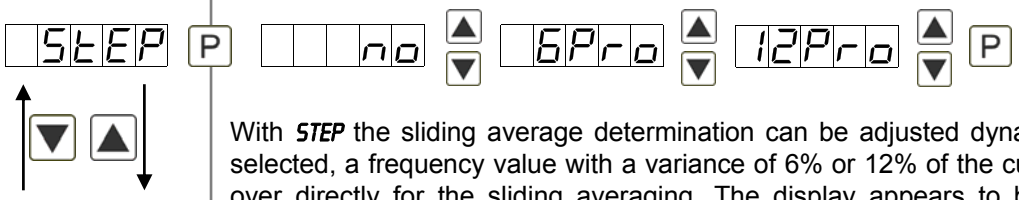
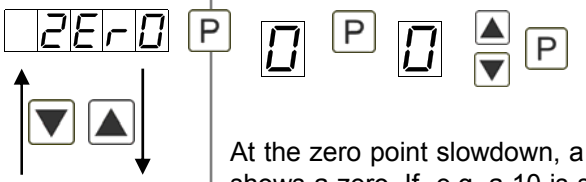
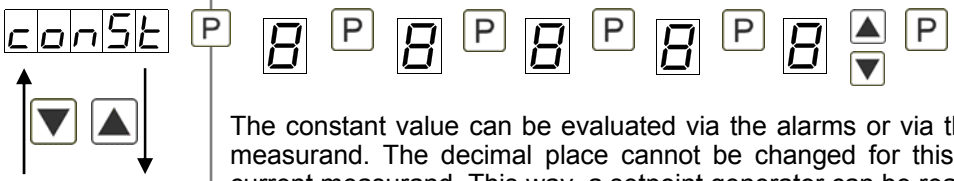
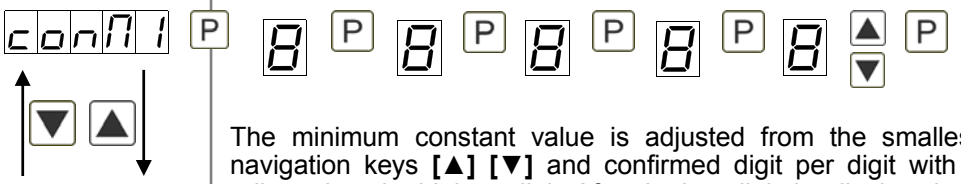
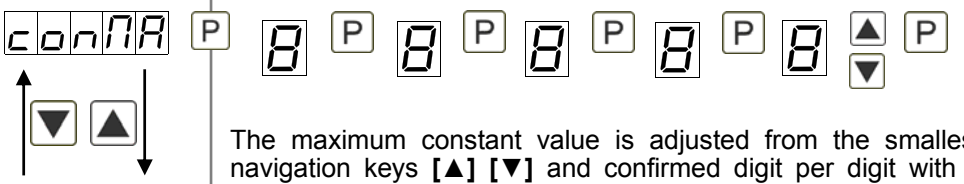
Menu level	Parameterisation level
dELAY	**Setting up the pulse delay, DELAY:** Default: 0 0 ▲▼ 250 ▲▼ P With the pulse delay of 0–250 seconds (maximum), frequencies can be collected, which are even smaller than by the predetermined measuring time of the device. If e.g. a delay of 250 seconds was set, this means that the device waits up to 250 seconds for an edge, before it assumes a 0Hz frequency. Thus frequencies up to 0.004Hz can be collected.
FI.Fr9	**Adjustment of the optimum digital frequency filter, FI.FRQ:** Default: NO no ▲▼ 100 ▲▼ 50 ▲▼ 20 ▲▼ 10 ▲▼ 5 ▲▼ 2 ▲▼ P If the optional filter is not activated by the adjustment NO, frequenices are ignored by the adjusted frequency filter. Act on the assumption that the pulse-duty factor is 1:1. Accordingly the minimal pulse duration is derived from half of the time of oscillation. Use a filter of 10Hz or 20Hz for contact bounce suppression.
FI.rAt	**Adjustment of the pulse-duty factor at activated digital filter, FI.RAT:** Default: 1-1 1-1 ▲▼ 1-3 ▲▼ 3-1 ▲▼ P Adjustment of the desired pulse-duty factor for pulse duration and pulse interruption. Like this, a special pulse behaviour can be adjusted.
tArA	**Setting up the tare/offset value, TARA:** Default: 0 0 P 0 P 0 P 0 P 0 ▲▼ P The given value is added to the linerarized value. This way, the characteristic line can be shifted by the selected amount.
SPCt	**Number of additional supporting points, SPCT:** Default: 00 0 ▲▼ 0 ▲▼ P 30 additional supporting points can be defined to the initial value and final value, so linear sensor values are not linearised. Only activated supporting point parameters are displayed.

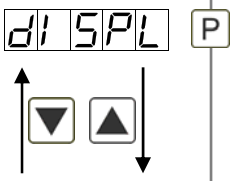
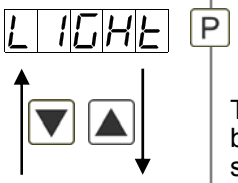
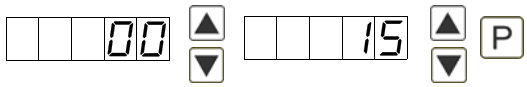
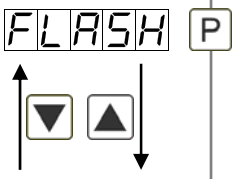
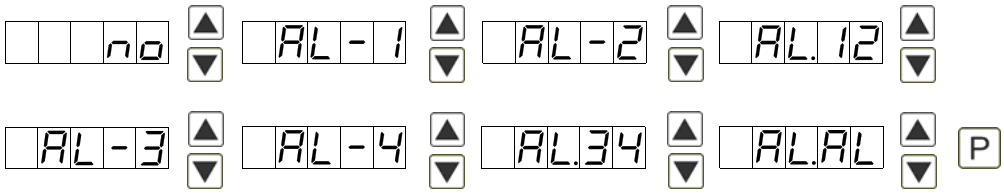
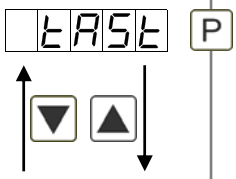
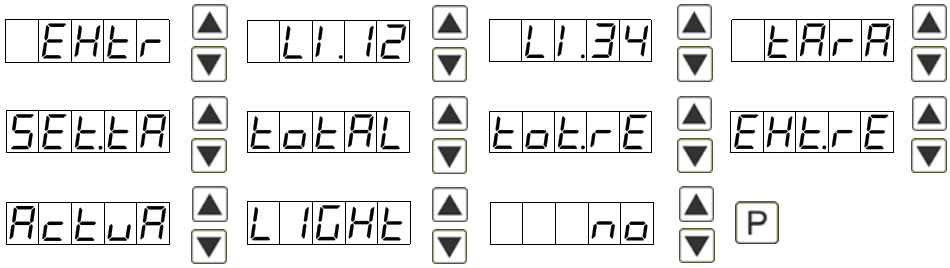
Menu level	Parameterisation level
	**Display values for supporting points,** *DIS.01 ... DIS.30:*  Under this parameter supporting points are defined according to their value. At the sensor calibration, like at final value/offset, one is asked at the end if a calibration shall be activated.
	**Analog values for supporting points,** *INP.01 ... INP.30:*  These supporting points are displayed at works setting (4-20 mA) only. Here, demanded analog values can be choosen freely. The input of steadily rising analog values needs to be done self-contained.
	**Display underflow,** *DI.UND:* Default: *-19999*  With this function the device undercut (_ _ _ _ _) can be defined on a definite value.
	**Display overflow,** *DI.OVE:* Default: *-19999*  With this function the device overflow (- - - - -) can be defined on a definite value.
	Input variable of process value, *SIG.IN*: **Default:** *A.MEAS*  This parameter controls the device via the analog input signals *A.MEAS* = *SENS.F* repectively *FREQU* or via the digital signals of the interface *M.BUS* = RS232/RS485 (Modbus protocol). Confirm the selction with **[P]** and the device changes back into menu level.
	**Back to menu group level,** *RET:* With **[P]** the selection is confirmed and the device changes into menu group level *„-INP-"*.

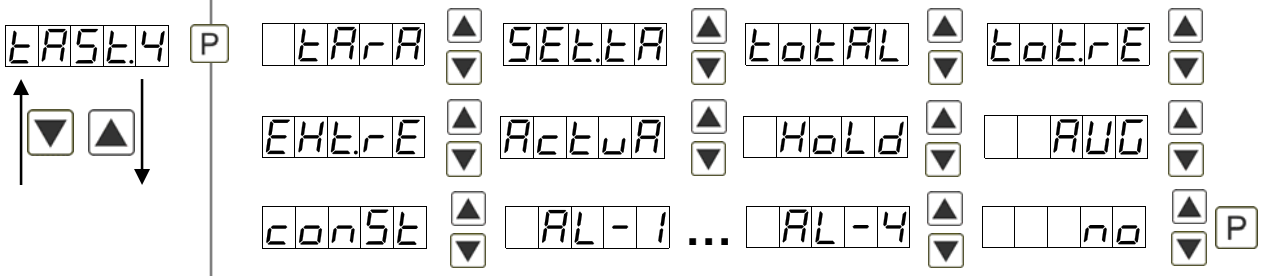
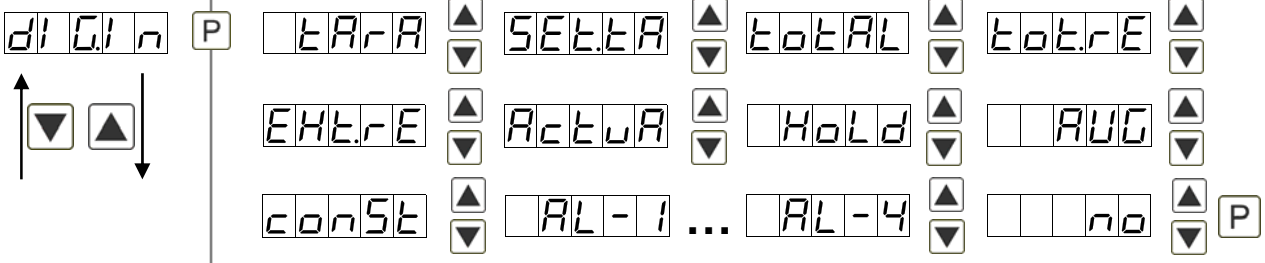
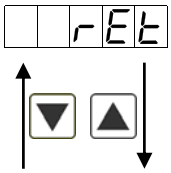
5.4.2. General device parameters



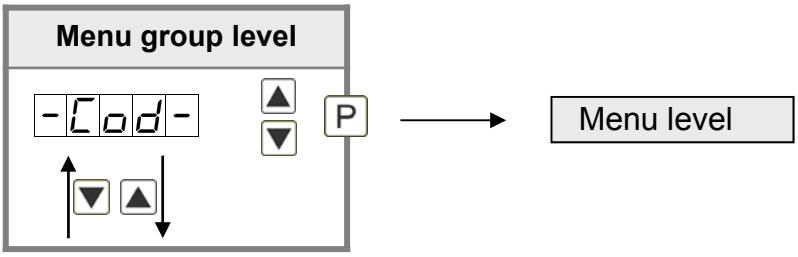
Menu level	Parameterisation level
	**Display time,** *DISEC:* Default: *01.0* The display is set up with **[▲] [▼]**. Thereby on switches until 1 second in 0.1 steps and until 10.0 seconds in 1.0-steps. With **[P]** the selection is confirmed and the device changes into menu level.
	**Rounding of display values,** *ROUND:* Default: *00001* This function is for instable display values, where the display value is changed in increments of 1, 5, 10 or 50. This does not affect the resolution of the optional outputs. With **[P]** the selection is confirmed and the device changes into menu level.
	**Arithmetic,** *ARITH:* Default: *NO* With this function the calculated value, not the measurand, is shown in the display. With *NO*, no calculation is deposited. With **[P]** the selection is confirmed and the device changes into menu level.
	**Sliding average determination,** *AVG:* Default: *10* Here, the number of the meterings that need to be averaged is preset. The time of averaging results of the product of measuring time *SEC* and the averaged metering *AVG*. With the selection of *AVG* in the menu level *DISPL*, the result will be shown in the display and evaluated via the alarms.

Menu level	Parameterisation level
	**Dynamic for the sliding average determination, STEP:** Default: NO With STEP the sliding average determination can be adjusted dynamically. If 6pro or 12pro is selected, a frequency value with a variance of 6% or 12% of the current display value is taken over directly for the sliding averaging. The display appears to be more dynamic at a fast frequency change, without appearing disturbed by a slightly unsteady frequency.
	**Zero point slowdown, ZERO:** Default: 00 At the zero point slowdown, a value range around the zero point can be preset, so the display shows a zero. If e.g. a 10 is set, the display would show a zero in the value range from -10 to +10; below continue with -11 and beyond with +11.
	**Definite contstant value, CONST:** Default: 0 The constant value can be evaluated via the alarms or via the analog output, like the current measurand. The decimal place cannot be changed for this value and is taken over by the current measurand. This way, a setpoint generator can be realised via the analog output by this value. Furthermore it can be used for calculating the difference. At this the constant value is substracted from the current measurand and the difference is evaluated in the alerting or by the analog output. Thus regulations can be displayed quite easily.
	**Minimum constant value, CON.MI:** Default: -19999 The minimum constant value is adjusted from the smallest to the highest digit with the navigation keys **[▲] [▼]** and confirmed digit per digit with **[P]**. A minus sign can only be adjusted on the highest digit. After the last digit the display changes back into menu level.
	**Maximum constant value, CON.MA:** Default: 99999 The maximum constant value is adjusted from the smallest to the highest digit with the navigation keys **[▲] [▼]** and confirmed digit per digit with **[P]**. A minus sign can only be adjusted on the highest digit. After the last digit the display changes back into menu level.

Menu level	Parameterisation level
	**Display,** *DISPL:* Default: *ACTUA*  With this function the current measurand, min/max value, totaliser value, the process-controlled Hold-value, the sliding average value, the constant value or the difference between constant value and current value can be allocated to the display. With **[P]** the selection is confirmed and the device changes into menu level.
	**Brightness control,** *LIGHT*: Default: *15*  The brightness of the display can be adjusted in 16 levels from 00 = very dark to 15 = very bright via this parameter or alternatively via the navigation keys from the outside. During the start of the device the level that is deposited under this parameter will always be used, even though the brightness has been changed via the navigation keys in the meantime.
	**Display flashing,** *FLASH:* Default: *NO*  A display flashing can be added as additional alarm function either to single or to a combination of off-limit condition. With *NO*, no flashing is allocated.
	**Assignment (deposit) of key functions,** *TAST:* Default: *NO*  For the operation mode, special functions can be deposited on the navigation keys **[▲] [▼]**, in particular this function is made for devices in housing size 48x24mm which do not have a 4th key (**[O]-key**). If the min/max-memory is activated with *EHTR*, all measured min/max-values are saved during operation and can be recalled via the navigation keys. The values get lost by restart of the device. If the threshold value correction *LI.12* or *LI.34* is choosen, the values of the threshold can be changed during operation without disturbing the operating procedure. With *TARA* the device is tared to zero and saved permanently as offset. The device confirms the correct taring by showing *00000* in the display. *SET.TA* switches into the offset value and can be changed via the navigation keys **[▲] [▼]**.

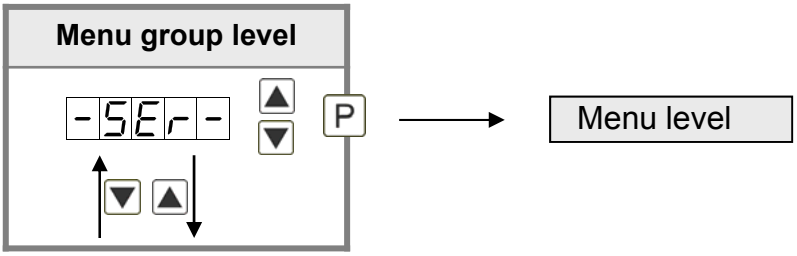
Menu level	Parameterisation level
Continuation	Via *TOTAL* the current value of the totaliser can be displayed, after this the device changes back onto the parameterised display value. If *TOT.RE* is deposited, the totaliser can be set back by pressing the navigation keys **[▲] [▼]**, the device acknowledges this with showing *00000* in the display. The configuration of *EHT.RE* deletes the min/max-memory. Under *ACTUA* the measurand is shown, after this the display returns to the parameterised display value. The brightness can be adjusted with *LIGHT*. This adjustment is not saved and gets lost at a restart of the device. If *NO* is selected, the navigation keys are without any function in the operation mode.
	**Special function [O]-key,** *TAST.4:* Default: *NO* For the operation mode, special functions can be deposited on the **[O]-key**. This function is activated by pressing the key. With *TARA* the device is set temporarily on a parameterised value. The device acknowledges the correct taring with *00000* in the display. *SET.TA* adds a defined value on to the currently displayed value. Via *TOTAL* the current value of the totaliser can be displayed, after this the device switches back on the parameterised display value. If *TOT.RE* was deposited, the totaliser can be set back by pressing of the navigation keys **[▲] [▼]**, the device acknowledges this with *00000* in the display. *EHT.RE* deletes the min/max-memory. If *HOLD* has been selected, the moment can be hold constant by pressing the **[O]-key**, and is updated by releasing the key. **Advice:** *HOLD* is activated only, if *HOLD* was selected under parameter *DISPL*. *ACTUA* shows the measuring value, after this the device switches back on the parameterised display value. The same goes for *AVG*, here the sliding average values will be displayed. The constant value *CONST* can be recalled via the digital input, or changed digit per digit. At *AL-1...AL-4* an output can be set and therewith e.g. a setpoint adjustment can be done. If *NO* is selected, the **[O]-key** is without any function in the operation mode.
	**Special function digital input,** *DIG.IN:* Default: *NO* In operation mode, the above shown parameter can be laid on the optional digital input, too. Function description see *TAST.4*.
	**Back to menu group level,** *RET*: With **[P]** the selection is confirmed and the device changes into menu group level „*-FCT-*".

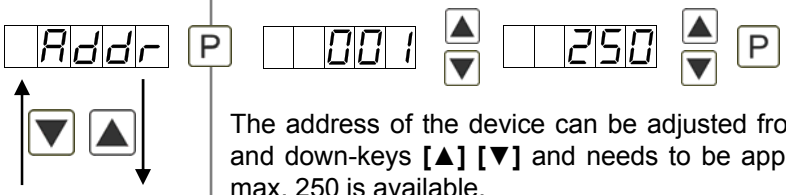
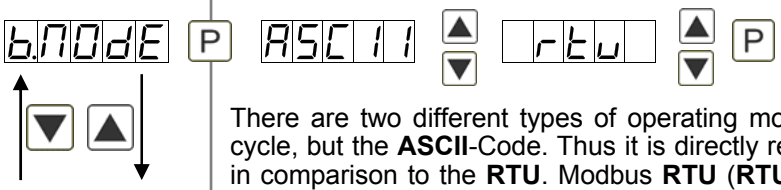
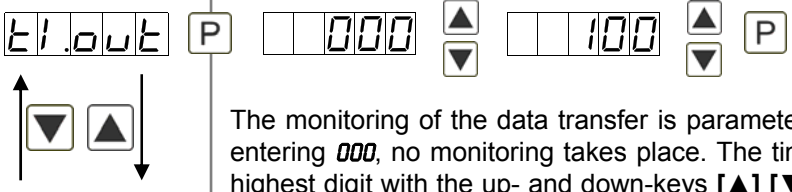
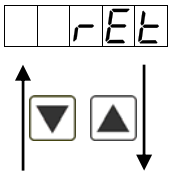
5.4.3. Safety parameters



Menu level	Parameterisation level
U.CodE P	**User code, U.CODE:** Default: 0000 0 P 0 P 0 P 0 P ▲▼ P Via this code reduced sets of parameters can released. A change of the U.CODE can be done via the correct input of the A.CODE (master code).
A.CodE P	**Master code, A.CODE:** Default: 1234 1 P 2 P 3 P 4 ▲▼ P By entering A.CODE the device will be unlocked and all parameters are released.
OutLE P	**Release/lock analog output parameters, OUT.LE:** Default: ALL no ▲▼ En-OF ▲▼ OutEO ▲▼ ALL ▲▼ P Analog output parameter can be locked or released for the user: - EN-OF: the initial or final value can be changed in operation mode - OUT.EO: the output signal can be changed from e.g. 0-20 mA to 4-20 mA or 0-10 VDC - ALL: analog output parameters are released - NO: all analog output parameters are locked
AL.LEU P	**Release/lock alarm parameters, AL.LEU:** Default: ALL no ▲▼ LIMIt ▲▼ ALrM.L ▲▼ ALL ▲▼ P This parameter describes the user release/user lock of the alarm: - LIMIT: here only the range of value of the threshold values 1-4 can be changed - ALRM.L: here the range of value and the alarm trigger can be changed - ALL: all alarm parameters are released - NO: all alarm parameters are locked
rEt	**Back to menu group level, RET:** With **[P]** the selection is confirmed and the device changes into menu group level „-COD-".

5.4.4. Serial parameters



Menu level	Parameterisation level
	**Device address, ADDR:** Default: 001 The address of the device can be adjusted from the smallest to the highest digit with the up- and down-keys **[▲] [▼]** and needs to be approved digit per digit with **[P]**. An address up to max. 250 is available. Interface data: Baudrate 9600 bit/s, 8 databyte, 1 stopbit, no parity (8n1).
	**ModBus operating modes, B.MODE:** Default: ASCII There are two different types of operating modes: ASCII and RTU. Modbus transfers no binary cycle, but the **ASCII**-Code. Thus it is directly readable, however the data throughput is smaller in comparison to the **RTU**. Modbus **RTU** (**RTU** = **R**emote **T**erminal **U**nit) transfers the data in binary-coded. This leads to a good data troughput, even though the data cannot be evaluated directly, as they first need to be transfered into a readable format.
	**Timeout, TIOUT:** Default: 000 The monitoring of the data transfer is parameterised in seconds, up to max. 100 seconds. By entering 000, no monitoring takes place. The timeout can be adjusted vom the smallest to the highest digit with the up- and down-keys **[▲] [▼]** and needs to be approved digit per digit with **[P]**. After the last digit, the display changes back into menu level.
	**Back to menu group level, RET:** With **[P]** the selection is confirmed and the device changes into menu group level „-SER-".

5.4.5. Analog output parameters 1

Menu group level
-Out- ▲ ▼ P → Menu level

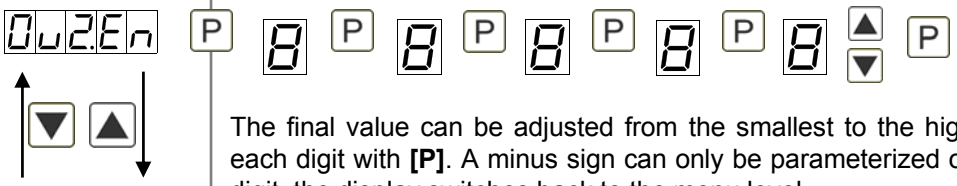
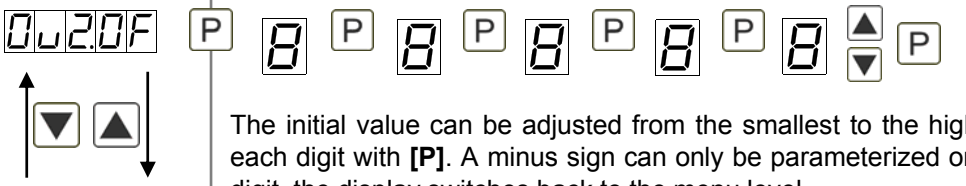
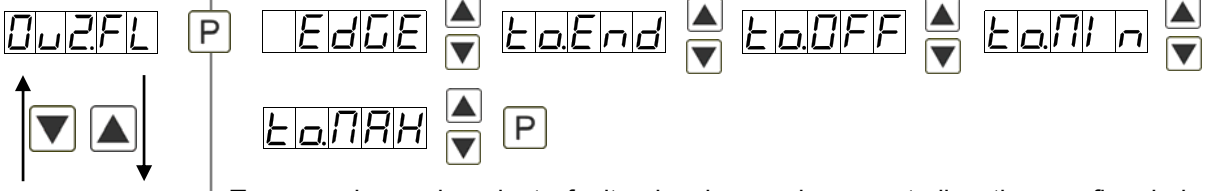
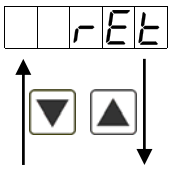
Menu level	Parameterisation level
OutPt P	**Selection reference of analog output, OUTPT:** Default: ACTUA ActuA ▲▼ MI n.UA ▲▼ MAH.UA ▲▼ totAL ▲▼ HoLd ▲▼ AUG ▲▼ conSt ▲▼ dIFF ▲▼ P The analog output signal can refer to different functions, in detail these are the current measurand, the min-value, the max-value, the totaliser/sum function, the constant value or the difference between current measurand and constant value. If HOLD was selected, the signal of the analog output will be kept. It can be continued processing after a deactivation of HOLD. With **[P]** the selection is confirmed and the device changes into menu level.
Out.rA P	**Selection analog output, OUT.RA:** Default: 4-20 0-10 ▲▼ 0-20 ▲▼ 4-20 ▲▼ P Three output signals are available 0-10 VDC, 0-20 mA and 4-20 mA. Select the desired signal with this function.
Out.En P	**Setting the upper value of the analog output, OUT.EN:** Default: 10000 8 P 8 P 8 P 8 P 8 P 8 ▲▼ P The final value is adjusted from the smallest to the highest digit with **[▲] [▼]** and confirmed digit per digit with **[P]**. A minus sign can only be parameterised on the leftmost digit. After the last digit the device changes back into menu level.
Out.OF P	**Setting the lower value of the analog output, OUT.OF:** Default: 00000 8 P 8 P 8 P 8 P 8 ▲▼ P The initial value is adjusted from the smallest to the highest digit with **[▲] [▼]** and confirmed digit per digit with **[P]**. A minus sign can only be parameterised on the leftmost digit. After the last digit the device changes back into menu level.

Menu level	Parameterisation level
O.FLOU P	**Overflow behaviour, O.FLOU:** Default: EDGE EdGE ▲▼ to.End ▲▼ to.OFF ▲▼ to.MIn ▲▼ to.MAH ▲▼ P To recognise and evaluate faulty signals, e.g. by a controller, the overflow behaviour of the analog output can be defined. As overflow can be seen either EDGE, that means the analog output runs on the set limits e.g. 4 and 20 mA, or TO.OFF (input value smaller than initial value, analog output switches on e.g. 4 mA), TO.END (higher than final value, analog output switchess on e.g. 20 mA). If TO.MIN or TO.MAX is set, the analog output switches onto the smallest or highest possible binary value. This means that values of e.g. 0 mA, 0 VDC or values higher than 20 mA or 10 VDC can be reached. With **[P]** the selection is confirmed and the device changes into menu level.
rEt	**Back to menu group level, RET:** With **[P]** the selection is confirmed and the device changes into menu group level „-OUT-".

Analog output parameters 2

Menu group level
-Ou2- ▲▼ P → Menu level

Menu level	Parameterisation level
Ou2.Pt P	**Selection reference analog output, OU2.PT:** Default: ACTUA ActuA ▲▼ MInUA ▲▼ MAHUA ▲▼ totAL ▲▼ HoLd ▲▼ AUG ▲▼ conSt ▲▼ dIFF ▲▼ P The analog output signal can refer to different functions, in detail this are the current measurand, min-value, max-value, totaliser/sum-function, the sliding average value, the constant value or the difference between the current measurand and the constant value. If HOLD is selected the signal of the analog output will be hold and processed just after deactivation of HOLD. With **[P]** the selection is confirmed and the device changes into menu level.
Ou2.rA P	**Selection analog output, OU2.RA:** Default: 4-20 0-10 ▲▼ 0-20 ▲▼ 4-20 P There are 3 output signals availabe: 0-10 VDC, 0-20 mA and 4-20 mA. With this function the demanded signal can be selected.

Menu level	Parameterisation level
	**Setting up the upper value of the analog output, OU2.EN:** Default: 001 The final value can be adjusted from the smallest to the highest digit with **[▲] [▼]**. Confirm each digit with **[P]**. A minus sign can only be parameterized on the leftmost digit. After the last digit, the display switches back to the menu level.
	**Setting up the lower value of the analog output, OU2.OF:** Default: 00000 The initial value can be adjusted from the smallest to the highest digit with **[▲] [▼]**. Confirm each digit with **[P]**. A minus sign can only be parameterized on the leftmost digit. After the last digit, the display switches back to the menu level.
	**Overflow behaviour, OU2.FL:** Default: EDGE To recognise and evaluate faulty signals, e.g. by a controller, the overflow behaviour of the analog output can be defined. As overflow can be seen either EDGE, that means the analog output runs on the set limits e.g. 4 and 20 mA, or TO.OFF (input value smaller than initial value, analog output switches on e.g. 4 mA), TO.END (higher than final value, analog output switches on e.g. 20 mA). If TO.MIN or TO.MAX is set, the analog output switches on the smallest or highest possible binary value. This means that values of e.g. 0 mA, 0 VDC or values higher than 20 mA or 10 VDC can be reached. With **[P]** the selection is confirmed and the device changes into menu level.
	**Back to menu group level, RET:** With **[P]** the selection is confirmed and the device changes into menu group level „-OU2-".

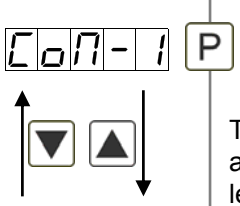
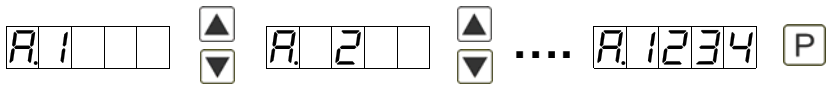
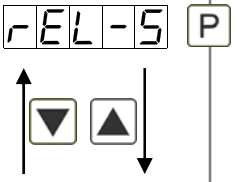
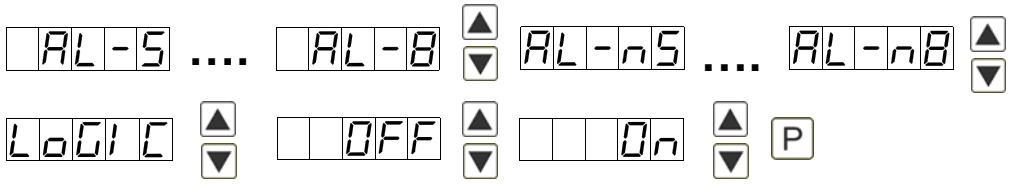
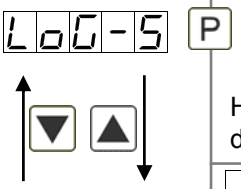
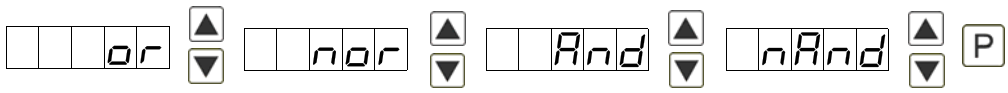
5.4.6. Relay functions

Menu group level
-rEL- ▲ ▼ P → Menu level
▼ ▲

Menu level	Parameterisation level
rEL-1 P ▼ ▲	**Alarm relay 1,** *REL-1*: **The same applies for relay 2-4** Default: *AL-1* AL-1 .... AL-4 ▲ ▼ AL-n1 .... AL-n4 ▲ ▼ LoGIC ▲ ▼ OFF ▲ ▼ On ▲ ▼ P Each setpoint (optional) can be linked up via 4 alarms (by default). This can either be inserted at activated alarms *AL1/4* or deactivated alarms *ALN1/4*. If *LOGIC* was selected, logical links are available in the menu level *LOG-1* and *COM-1*. Access to these two menu levels is via *LOGIC*, at all other selected functions, these two parameters are overleaped. Via *ON/OFF* the setpoints can be activated/deactivated, in this case the output and the setpoint display are set/not set on the front of the device. With **[P]** the selection is confirmed and the device changes into menu level.
LoG-1 P ▼ ▲	**Logic relay 1,** *LOG-1*: Default: *OR* or ▲ ▼ nor ▲ ▼ And ▲ ▼ nAnd ▲ ▼ P Here, the switching behaviour of the relay is defined via a logic link, the following schema describes these functions with inclusion of *AL-1* and *AL-2*:

or	*A1* v *A2*	As soon as a selected alarm is activated, the relay operates. Equates to operating current principle.
nor	$\overline{A1 \vee A2} = \overline{A1} \wedge \overline{A2}$	The relay operates only, if no selected alarm is active. Equates to quiescent current principle.
And	A1 ∧ a2	The relay operates only, if all selected alarms are active.
nAnd	$\overline{A1 \wedge A2} = \overline{A1} \vee \overline{A2}$	As soon as a selected alarm is not activated, the relay operates.

With **[P]** the selection is confirmed and the device changes into menu level.

Menu level	Parameterisation level
	**Alarms for relay 1, COM-1:** Default: A.1  The allocation of the alarms to relay 1 happens via this parameter, one alarm or a group of alarms can be chosen. With **[P]** the selection is confirmed and the device changes into menu level.
	**Alarm relay 5, REL-5:** **The same applies for relays 6-8** Default: AL-5  Each setpoint (optional) can be linked up via 4 alarms (by default). This can either be inserted at activated alarms AL6/8 or deactivated alarms ALN6/8. If LOGIC is selected, logical links are available in the menu level LOG-1 and COM-1. Access to these two menu levels is via LOGIC, at all other selected functions, these two parameters are overleaped. Via ON/OFF the setpoints can be activated/deactivated, in this case the output and the setpoint display are set/not set on the front of the device. With **[P]** the selection is confirmed and the device changes into menu level.
	**Logic relay 5, LOG-5:** Default: OR  Here, the switching behaviour of the relay is defined via a logic link, the following schema describes these functions with inclusion of AL-1 and AL-2:

or	$A1 \vee A2$	As soon as a selected alarm is activated, the relay operates. Equates to operating current principle.
nor	$\overline{A1 \vee A2} = \overline{A1} \wedge \overline{A2}$	The relay operates only, if no selected alarm is active. Equates to quiescent current principle.
And	$A1 \wedge a2$	The relay operates only, if all selected alarms are active.
nAnd	$\overline{A1 \wedge A2} = \overline{A1} \vee \overline{A2}$	As soon as a selected alarm is not activated, the relay operates.

With **[P]** the selection is confirmed and the device changes into menu level.

Menu level	Parameterisation level
CoM-5	**Alarms for relay 5,** COM-5: Default: A. 5 CoM-5 [P] A.5 ▲▼ A. 6 ▲▼ .... A.5678 ▲▼ [P] The allocation of the alarms for relay 5 happens via this parameter, one alarm or a group of alarms can be chosen. With **[P]** the selection is confirmed and the device changes into menu level.
rEt	**Back to menu group level,** RET: With **[P]** the selection is confirmed and the device changes into menu group level „-REL-".

5.4.7. Alarm parameters

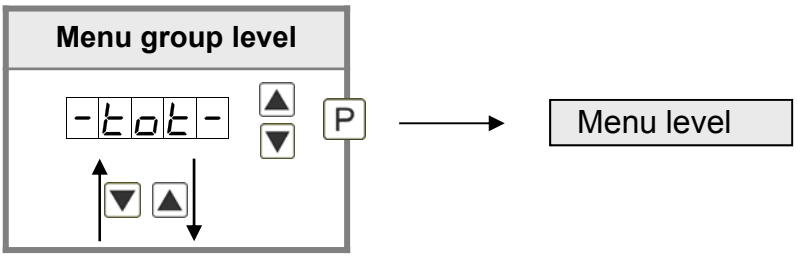
Menu group level
-AL 1- ▲▼ [P] → Menu level

Menu level	Parameterisation level
ALrM.1	**Dependency alarm 1,** ALRM.1: Default: ACTUA ALrM.1 [P] ACtuA ▲▼ MIn.UA ▲▼ MAX.UA ▲▼ totAL ▲▼ HoLd ▲▼ AUG ▲▼ const ▲▼ diFF ▲▼ EXtEr ▲▼ [P] The dependency of alarm 1 can be related to special functions, in detail these are the current measurand, the min-value, the max-value, the totaliser value/sum value, the constant value or the difference between the current measurand and the constant value. If HOLD was selected, then the alarm is held and processed just after deactivation of HOLD. EXTER causes the dependency either by pressing the **[O]-key** on the front of the housing or by an external signal via the digital input. With **[P]** the selection is confirmed and the device changes into menu level. **Example:** By using the maximum value ALARM.1 = MAX.VA in combination with a threshold monitoring FU-1 = HIGH, an alarm confirmation can be realised. Use the navigation keys, the 4th key or the digital input for confirmation.

Menu level	Parameterisation level
L1-1	**Threshold values / limit values, LI-1:** Default: 2000 P 0 P 0 P 0 P 0 P 0 ▲▼ P For both limit values, two different values can be parameterized. Like this, the parameters for each limit value are called up one after another.
HY-1	**Hysteresis for limit values, HY-1:** Default: 00000 P 0 P 0 P 0 P 0 P 0 ▲▼ P For all limit values exists a hysteresis function, that reacts according to the settings (threshold exceedance / threshold undercut).
Fu-1	**Function for threshold value exceedance/undercut, FU-1:** Default: HIGH P HIGH ▲▼ LOUU ▲▼ P The limit value undercut can be selected with LOUU (LOW = lower limit value) and limit value exceedance can be selected with HIGH (HIGH = upper limit value). If e.g. limit value 1 is on a switching threshold of 100 and occupied with function „HIGH“, the alarm will be activated by reaching the threshold. If the limit value is allocated to „LOW“, an alarm will be activated by undercut of the threshold.
ton-1	**Switching-on delay, TON-1:** Default: 000 P 0 P 0 P 0 P 0 P 0 ▲▼ P For limit value 1 one can preset a delayed switching-on of 0-100 seconds.
toF-1	**Switching-off delay, TOF-1:** Default: 000 P 0 P 0 P 0 P 0 P 0 ▲▼ P For limit value 1 one can preset a delayed switching-off of 0-100 seconds.
rEt	**Back to menu group level, RET:** With **[P]** the selection is confirmed and the device changes into menu group level „-AL1-“.

The same applies to -AL2- to -AL8-.

5.4.8. Totaliser (Volume measurement)



Menu level	Parameterisation level
totAL P	**Totaliser state, TOTAL:** Default: OFF totAL P OFF ▲▼ StEAd ▲▼ tEMP ▲▼ P The totaliser makes measurements on a time base of e.g. l/h possible, at this the scaled input signal is integrated by a time and steadily (select STEAD) or temporarily (select TEMP) safed. If OFF is selected, the function is deactivated. With **[P]** the selection is confirmed and the device changes into menu level.
t.bASE P	**Time base, T.BASE:** Default: SEC t.bASE P SEC ▲▼ Min ▲▼ hour ▲▼ P Under this parameter the time base of the measurement can be preset in seconds, minutes or hours.
FActo P	**Totaliser factor, FACTO:** Default: 10^{0} FActo P 10^{0} ▲▼ … 10^{6} ▲▼ P At this the factor (10^0…10^6) respectively the divisor for the internal calculation of the measuring value is assigned.
tot.dt P	**Setting up the decimal point for the totaliser, TOT.DT:** Default: 0 tot.dt P 0 ▲▼ 0.0 ▲▼ 0.00 ▲▼ 0.000 ▲▼ 0.0000 ▲▼ P The decimal point of the device can be adjusted with the navigation keys **[▲] [▼]**. With **[P]** the selection is confirmed and the device changes into menu level.

Menu level	Parameterisation level
tot.rE	**Totaliser reset,** *TOT.RE:* Default: *00000* P 8 P 8 P 8 P 8 P 8 ▲ ▼ P The reset value is adjusted from the smallest to the highest digit with the navigation keys **[▲] [▼]** and digit per digit confirmed with **[P]**. After the last digit, the display switches back to the menu level. The activator for the reset is parameter driven via the 4th key or via the optional digital input.
rEt	**Back to menu group level,** *RET*: With **[P]** the selection is confirmed and the device changes into menu group level „*-TOT-*“.

Programming lock, *RUN*:

Menu group level
-run- ▲ ▼ P Description see page 12, menu level *RUN*

6. Reset to factory settings

To return the unit to a **defined basic state**, a reset can be carried out to the default values.
The following procedure should be used:

- Switch off the power supply
- Press **[P]** button
- Switch on voltage supply and press **[P]-**button until „- - - - -“ is shown in the display.

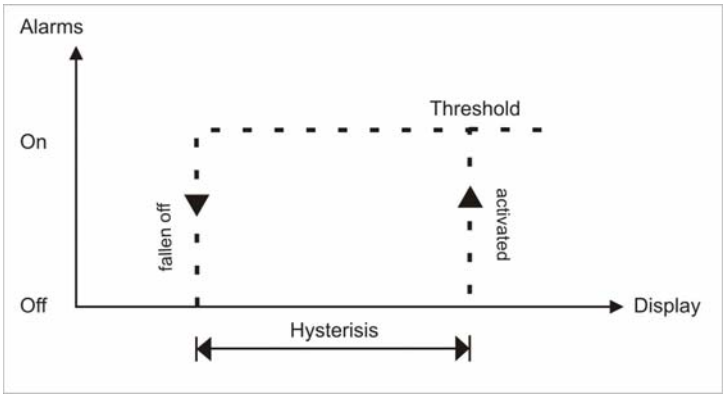
With reset, the default values of the program table are loaded and used for subsequent operation.
This sets the unit back to the state in which it was supplied.

Caution! All application-related data are lost.

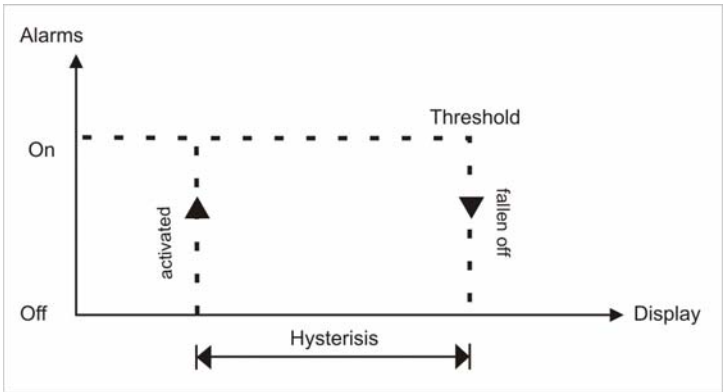
7. Alarms / Relays

This device has 4 virtual alarms that can monitor one limit value in regard of an undercut or exceedance. Each alarm can be allocated to an optional relay output S1-S4; furthermore alarms can be controlled by events like e.g. hold or min/max-value.

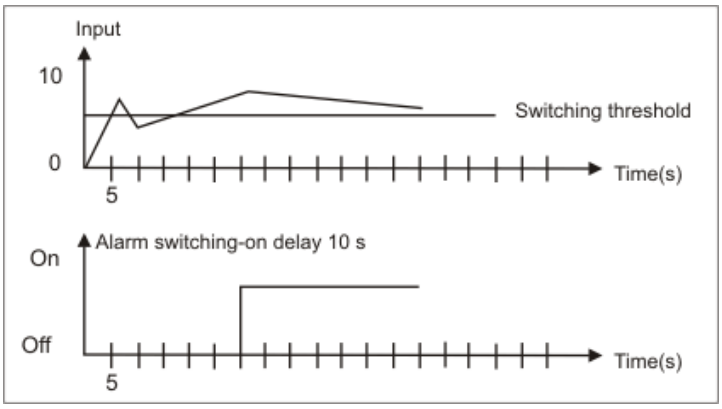
Function principle of alarms / relays	
Alarm / Relay x	Deactivated, instantaneous value, min/max-value, hold-value, totaliser value, sliding average value, constant value, difference between instantaneous value and constant value or an activation via the digital input or via the **[O]-key**.
Switching threshold	Threshold / limit value of the change-over
Hysteresis	Broadness of the window between the switching thresholds
Working principle	Operating current / Quiescent current



Operating current
By operating current, the alarm S1-S2 is **off** below the threshold and **on** on reaching the threshold.



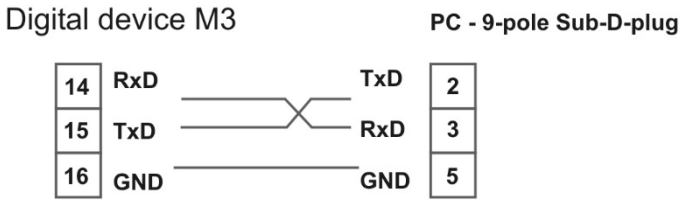
Quiescent current
By quiescent current the alarm S1-S2 is **on** below the threshold and switched **off** on reaching the threshold.



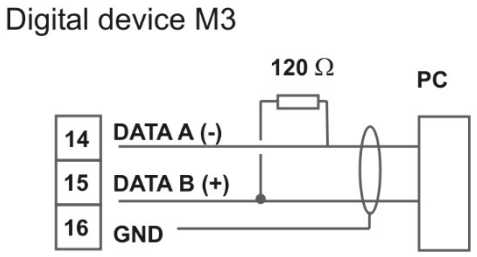
Switching-on delay
The switching-on delay is activated via an alarm and e.g. switched 10 seconds after reaching the switching threshold, a short-term exceedance of the switching value does not cause an alarm, respectively does not cause a switching operation of the relay. The switching-off delay operates in the same way, keeps the alarm / the relay switched longer for the parameterised time.

8. Interfaces RS232 and RS485

Connection RS232



Connection RS485



The interface **RS485** is connected via a screened data line with twisted wires (Twisted-Pair). On each end of the bus segment a termination of the bus lines needs to be connected. This is neccessary to ensure a secure data transfer to the bus. For this a resistance (120 Ohm) is interposed between the lines Data B (+) and Data A (–).

9. Programmer examples

Example for the rotation speed adjustment:

In this application the rotation speed of an axis shall be collected via a toothed wheel with 30 sprockets, per Namur sensor. It is then displayed with one position after decimal point and the dimension rpm.

Parameter	Settings	Description
tYPE	rotAr	Rotation – rotation speed measurement up to 10 kHz
PPr	30	Number of sprockets
dot	0.0	1 position after decimal point

Advice: The input frequency may be maximum 9.999 kHz in this operating module. So, a rotation speed parameterisation via the frequency adjustment is rarely necessary.

Example for the position coverage:

A measuring system for length works via an incremental encoder with two dephased output signals (typically A and B) and 100 pulse/rotation. The axis perimeter was calculated in a way that the measuring section can be extracted by a rotation of 6 cm = 60 mm. The display shall show the relative position in millimeter. There is a zero point position with a limit switch, that can zero the display if required.

Parameter	Settings	Description
tYPE	PoSIt	Positioning – rotary encoder
PPr	100	Pulse number per rotation
End	60	Change of length per rotation
dIG.In	tArA	Display zero

Advice: The display starts always on position zero. The parameter *DIG.IN* can be found under parameter group *-FCT-* in the extended parameterisation *PROF*.

Example for angle coverage:

On a manually operated bender for sheet metal the bending angle shall be displayed in degree. The device is in zero state (0°) during switching on of the display. An incremental encoder with 360 pulses/rotation is used.

Parameter	Settings	Description
tYPE	PoSIt	Positioning – rotary encoder
PPr	360	Pulse number per rotation
End	360	Angle sum per rotation

Examples: Adjustment according to number of sprockets at unknown rotation speed.

- nearly 100% of the rotation speeds are in the range of 0 to 30.000 r.p.m.
- the number of sprockets varies (without gearing) between 1 and 100
- in automation, the frequency supply never exceeds 10 kHz (rather 3 kHz)

Assume a rotation speed of 60 r.p.m. at 1 Hz, whereat the real frequency value will not be considered.

Our example complies with a number of sprockets of 64.

Setting up the advice

Based on the default settings of the display, the following parameters need to be changed:

Parameter	Settings	Description
tYPE	FrEqU	Applying of the measuring signal is not applicable.
rAnGE	1E3	Complies with 9.9999 Hz
End	6	Assumed final value
EndA	0.0064	Complies with 64 sprockets

If the frequency needs to be displayed with a position after decimal point, then a 60 has to be selected as final value for this adjustment.

Parameter	Settings	Description
tYPE	FrEqU	Applying of the measuring signal is not applicable.
rAnGE	1E3	Complies with 9.9999 Hz
End	60	Assumed final value
dot	0.0	1 position after decimal point
EndA	0.0064	Complies with 64 sprockets

Example: Rotation speed of a machine shaft

There are 4 sprockets on one machine shaft. Applied in an angle of 90° to each other and to the rotation speed measurement. The sprockets are collected via a proximity switch and evaluated by the frequency device, which shall display the rotation speed in U/min.
0…3600 U/min is preset as rotation speed range of the machine.

Calculation of the input frequency

Number of sprockets = 4
Rotation speed = 3600 U/min

$$\text{Final frequency [Hz]} = \frac{\text{Final rotation speed } [\frac{U}{\text{min}}]}{60 \; [\frac{s}{\text{min}}] \times 1U} \times \text{Number of sprockets}$$

$$\text{Final frequency [Hz]} = \frac{3600 \; \frac{U}{\text{min}}}{60 \; \frac{s}{\text{min}} \times 1U} \times 4 = 240 \; Hz$$

Setting up the device

Based on the default settings of the device, following parameters need to be changed:

Parameter	Settings	Description
tYPE	FrEQU	As the input frequency is known, the device does not need to be applied to the measuring section.
rAnGE	100E0	The final frequency is in the range of 100.00 to 999.99 Hz.
End	3600	A rotation speed of 3600 shall be displayed as final value.
EndA	240.00	The final frequency for display value 3600 is 24.00 Hz.

10. Technical data

Housing	
Dimensions	96x48x120 mm (WxHxD)
	96x48x139 mm (WxHxD) incl. plug-in terminal
Panel cut-out	$92.0^{+0,8}$ x $45.0^{+0,6}$ mm
Wall thickness	to 15 mm
Fixing	screw elements
Material	PC Polycarbonate, black, UL94V-0
Sealing material	EPDM, 65 Shore, black
Protection class	standard IP65 (front), IP00 (back side)
Weight	approx. 300 g
Connection	plug-in terminal; wire cross section up to 2.5 mm^2
Display	
Digit height	14 mm
Segment colour	red (optional green, orange)
Range of display	-19999 to 99999
Switching points	one LED per switching point
Overflow	horizontal bars at the top
Underflow	horizontal bars at the bottom
Display time	0.1 to 10.0 seconds
Input	
Sensing device	Namur, 3-wire initiator, pulse input
HTL level TTL level	> 15 V / < 4 V – U_{in} max. 30 V > 4.6 V / < 1.9 V
Input frequency	0.01 Hz – 999.99 kHz 0.01 Hz – 9.9999 kHz at rotation speed function ROTAR 0 – 2.5000 kHz at position identification POSIT
Input resistance	R_I at 24 V / 4 kΩ / R_I at Namur 1.8 kΩ
Frequency filter	none, 100 Hz, 50 Hz, 20 Hz, 10 Hz, 5 Hz, 2 Hz
Digital input	<2.4 V OFF, >10 V ON, max. 30 VDC R_I ~ 5 kΩ
Accuracy	
Temperature drift	50 ppm / K
Measuring time	0.1…10.0 seconds
Measuring principle	frequency measuring / pulse width modulation
Measuring error	0.05% of measuring range; ±1 digit
Resolution	approx. 19 bit per measuring range

Output	
Sensor supply	24 VDC / 50 mA
Analog output	0/4-20 mA / burden ≤500 Ω or 0-10 VDC / ≥10 kΩ, 16 bit
Switching outputs	
Relay Switching cycles	with change-over contacts 250 VAC / 5 AAC; 30 VDC / 5 ADC 30 x 10^3 at 5 AAC, 5 ADC ohm resistive load 10 x 10^6 mechanically Diversity according to DIN EN50178 / Characteristics according to DIN EN60255
PhotoMos outputs	Normally open contact: 30 VDC/AC, 0.4 A
Interface	
Protocol	Modbus with ASCII or RTU-protocol
RS232	9.600 Baud, no parity, 8 databit, 1 stopbit, wire length max. 3 m
RS485	9.600 Baud, no parity, 8 databit, 1 stopbit, wire length max 1000 m
Power supply	100-240 VAC, DC ± 10% (max. 15 VA) 10-40 VDC galv. isolated, 18-30 VAC 50/60 Hz (max. 15 VA)
Memory	EEPROM
Data life	≥ 100 years at 25°C
Ambient conditions	
Working temperature	0…50°C
Storing temperature	-20…80°C
Climatic density	relative humidity 0-80% on years average without dew
Height	up to 200m above sea level
EMV	EN 61326, EN 55011
CE-sign	Conformity to directive 2014/30/EU
Safety standard	According to low voltage directive 2014/35/EU EN 61010; EN 60664-1

11. Safety advices

Please read the following safety advices and the assembly *chapter 2* before installation and keep it for future reference.

Proper use

The **AZ20.F -device** is designed for the evaluation and display of sensor signals.

Danger! Careless use or improper operation can result in personal injury and/or cause damage to the equipment.

Control of the device

The panel meters are checked before dispatch and sent out in perfect condition. Should there be any visible damage, we recommend close examination of the packaging. Please inform the supplier immediately of any damage.

Installation

The**AZ20.F-device** must be installed by a suitably **qualified specialist** (e.g. with a qualification in industrial electronics).

Notes on installation

- There must be no magnetic or electric fields in the vicinity of the device, e.g. due to transformers, mobile phones or electrostatic discharge.
- **The fuse rating of the supply voltage should not exceed a value of 0.5A N.B. fuse!**
- Do not install **inductive consumers** (relays, solenoid valves etc.) near the device and **suppress** any interference with the aid of RC spark extinguishing combinations or free-wheeling diodes.
- Keep input, output and supply lines separate from one another and do not lay them parallel with each other. Position “go” and “return lines” next to one another. Where possible use twisted pair. So, you receive best measuring results.
- Screen off and twist sensor lines. Do not lay current-carrying lines in the vicinity. Connect the **screening on one side** on a suitable potential equaliser (normally signal ground).
- The device is not suitable for installation in areas where there is a risk of explosion.
- Any electrical connection deviating from the connection diagram can endanger human life and/or can destroy the equipment.
- The terminal area of the devices is part of the service. Here electrostatic discharge needs to be avoided. Attention! High voltages can cause dangerous body currents.
- Galvanic isolated potentials within one complex need to be placed on an appropriate point (normally earth or machines ground). So, a lower disturbance sensibility against impacted energy can be reached and dangerous potentials, that can occur on long lines or due to faulty wiring, can be avoided.

12. Error elimination

	Error description	Measures
1.	The device shows a permanent overflow	• The input frequency is too high for the selected frequency range. Correct RANGE according to this. • Disturbing pulses lead to an increased input frequency, activate FI.FRQ at smaller frequencies or shield the senor line. • A mechanic switching contact chatters. Activate the frequency filter FI.FRQ with 10 or 20 kHz. • The display was taught faulty under TYPE = SENS.F. Error elimination see below.
2.	The device shows a permanent underflow.	• An offset frequency OFFSA bigger than 0 Hz respectively a „Living zero“ was selected, in which no frequency is aligned. Check the sensor lines or set the OFFSA onto 0 Hz. • The display underflow DL.UND was selected too high. The according parameter needs to be adapted. • The device was taught faulty under TYPE = SENS.F. Error elimination see below.
3.	The displayed values switches sporadical.	• Disturbances lead to short-term display switches. For smaller frequences use the frequency filter FI.FRQ, select a higher measuring time or use the sliding averaging. • The sprockets that needs to be collected are not evenly spread on a shaft or are not measured accurately. Use the sliding averaging „AVG“ if necessary with the dynamic function STEP. The displayed value DISPL needs to be set on AVG.
4.	The display remains on zero.	• The sensor was not connected properly. Check the connection lines and if necessary the sensor supply. Best directly on the screw terminals of the device! • A PNP- respectively NPN-output does not reach the required threshold. Check the voltage between terminal 2 and 3 with a multimeter. Depending on signal form it generally shoud be between 4 V and 15 V. The thresholds can be checked more savely with an oscilloscope. If necessary include an external pull-up or pull-down. • A Namur-sensor does not react. Check the distance between the sensor and the sprocket / survey mark and if necessary measure the voltage between 1 & 3. In open condition the input voltage needs to be smaller than 2.2 V and in active condition bigger than 4.6 V. • The selected range of the input frequency is too high. Reduce the frequency range RANGE to a smaller value. • The activated frequency filter FI.FRQ suppresses the relevant pulses. Increase the filter frequency FI.FRQ or use the adaption of the key proportion FI.RAT. If this should not work, temporarily deactivate the frequency filter with FI.FRQ = NO. • The device was taught faulty under TYPE = SENS.F. Change into TYPE / FREQU and preset the assumed frequency range RANGE and the according initial and final values END, OFFS, ENDA, and OFFSA. Check this way, if a frequency signal was connected to the input.
5.	The device shows HELP in the 7-segment display	• The device located an error in the configuration memory, excecute a reset to the default values and set up the device according to your application.
6.	Program numbers for the parameterisation of the input are not available	• The programming interlock is activated. • Enter correct code.
7.	The device shows ERR1 in the 7-segment display	• Contact the manufacturer if errors of this kind occur.
8.	The device does not react as expected.	• If you are not sure, if the device has been parameterised before, restore the state of delivery as described in *chapter 6*.

AZ20

Digital LED Display- and Control Unit for Panel Mounting 5 Digit

- **for all standard signals**
- **individually programmable**
- **alarm functions**
- **limit value outputs**
- **min/max-memory**
- **totaliser function**
- **frequency analogue converter**
- **characteristic adaption**
- **red, orange, green, blue or tricolor LEDs**

Description:

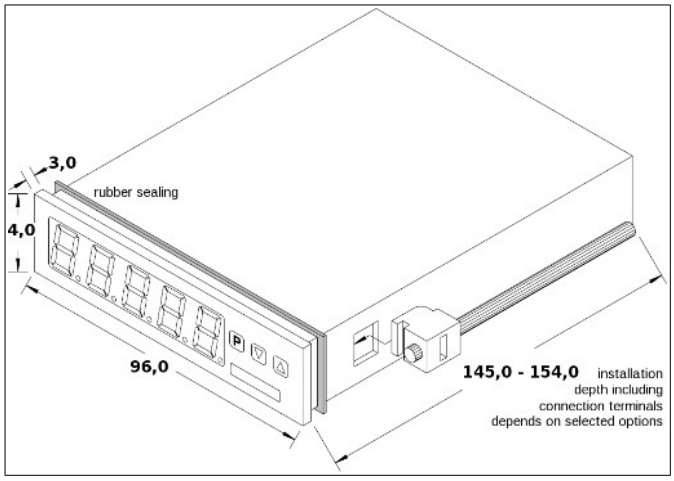
The panel mounted devices of the AZ20 series are designed for the display and evaluation of standard signals common in industry. Input modules for voltage, current, Pt100, thermocouples and frequency are available. Thanks to optional sensor supply and additional analogue output, the devices are suitable for almost all application areas. Additional serial interfaces according to the RS232 or RS485 specification give the AZ20 additional flexibility. An individual characteristics adaption with up to 30 interpolation points allows the use even in difficult cases of measurement and control technology. All settings can be easily programmed via the membrane keypad on the device or via software from PC or laptop on site. The optional tricolor LEDs provide a clearly visible visualization of the respective operating status, especially when set limit values are exceeded, even over long distances.

Typical applications:

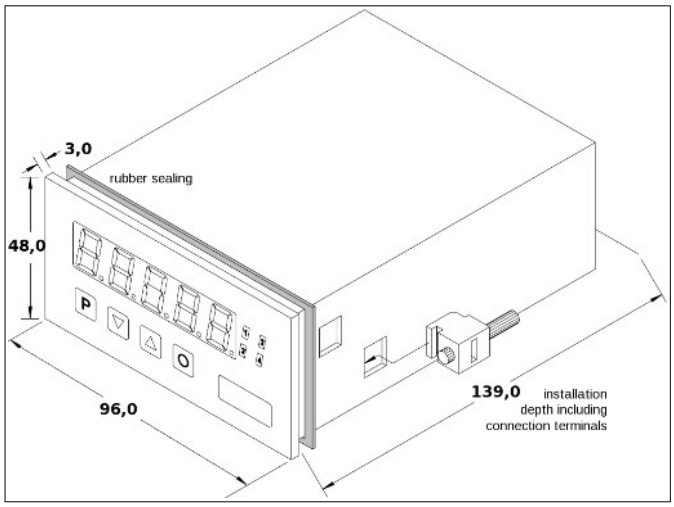
Due to the large variety of combinations of input signals and output configurations, the AZ20 has practically no limits in industrial and laboratory applications.

Models:

AZ20.2:
96 x 24 mm, for panel cut-out 92,0 x 22,2 mm:



AZ20.4
96 x 48 mm, for panel cut-out 92,0 x 45,0 mm:



Technical Data:

Display: 5 digit LED display, optionally red, orange, green, blue or tricolor (green ↑ orange ↑ red, depending on operating status), 14 mm high

range: -19999 … 99999

integration time: 0,1 … 10 seconds

Housing: polycarbonate black
gasket EPDM black

Protection class: front side IP65 standard
rear side IP00

Temperature:

operating temperature: 0 … +50 °C

storage temperature: -20 … +80 °C

Input signals:

voltage: 0 … 10 VDC (-12 … +12 VDC max)
Ri approx. 200 kΩ
accuracy 0,1 % of range,
±1 digit; 100 ppm/K temperature drift

current: 0 (4) … 20 mA (-22 … 24 mA max)
Ri approx. 100 Ω
accuracy 0,1 % of range
±1 digit; 100 ppm/K temperature drift

frequency: 0,01 Hz … 999,99 kHz
pulse input, TTL, Namur,
3-wire initiator PNP/NPN
Ri at 24 V approx. 4 kΩ
high/low level > 15 V / < 4 V
TTL: > 4,6 V / < 1,9 V
accuracy 0,05 % of range
±1 Digit

Pt100: -200 … 850 °C, resolution 0,1 °C
accuracy 0,1 % of range
±1 Digit; 100 ppm/K temperature drift

thermocouple:

type B	80	…	1820 °C
type E	-270	…	1000 °C
type J	-210	…	1200 °C
type K	-270	…	1372 °C
type L	-200	…	900 °C
type N	-270	…	1300 °C
type S	-50	…	1768 °C
type T	-270	…	400 °C
type R	-50	…	1768 °C

resolution 0,1 °C
accuracy 2 K, ±1 digit
100 ppm/K temperature drift
characteristic error < ±1 K

resistance chain: 3-wire potentiometer 0...100 %
measuring span: 1 kΩ…1 MΩ

digital input: galvanically isolated
< 2,4 V OFF, 10 V ON, 30 V max
Ri approx. 5 kΩ

Analogue output: 4(0) … 20 mA; 0 … 10 V
16 bit resolution

Switching output:

relay: SPDT contact, 250 V / 5 AAC,
30 V / 5 ADC
> 30000 switch. cycles at 30 V / 5 A
ohms, > 1000000 mechanical

Foto MOS-Fet: N/O contact,
30 VDC/AC, 400 mA

Sensor supply: 24 VDC, 50 mA; 10 VDC, 20 mA

Interfaces:

RS232: 9600 baud, no parity, 8 data, 1 stop
max 3 m cable length

RS485: 9600 baud, no parity, 8 data, 1 stop
max 1000 m cable length

Supply: adapter 230 VAC, max 20 VA
10 … 30 VDC, max 8 VA
galvanically isolated

Memory: EEPROM, date retention > 100 years

Order Code:

Order number: **AZ20.** **4.** **I.** **1.** **A.** **R2.** **2.** **0.** **R**

Digital LED display- and control unit for panel mounting, 5 digits

Models:
2 = installation dimension 24 x 96 mm
4 = installation dimension 48 x 96 mm

Input signals:
I = 0(4) … 20 mA; 0 … 10 V
F = frequencv – pulses
T = thermocouple
P = Pt100
W = resistance measuring chain

Power supply:
1 = 230 VAC
2 = 10 … 30 VDC

Analogue output signal:
0 = without output signal
A = analogue output 0(4)…20 mA; 0…10 V
AA = 2 analogue outputs 0(4)…20 mA; 0…10 V (only for version 48 x 96 mm)

Switching outputs:
0 = without switching output
R2 = with 2 relay outputs
R4 = with 4 relay outputs (only for version 48 x 96 mm)
M8 = with 8 photo MOSFET outputs (only for version 48 x 96 mm)

Sensor supply:
0 = without
1 = with 10 VDC
2 = with 24 VDC

Interface:
0 = without
S2 = serial interface RS232
S4 = serial interface RS485

Display color:
R = red LEDs
Y = yellow.orange LEDs
G = green LEDs
B = blue LEDs
T = tricolor LEDs (green ↑ orange ↑ red, acc. to operating status)

Options (combinable):
0 = without
S = software for parameterisation
U = USB cable for PC connection
D = digital input (included with sensor supply)

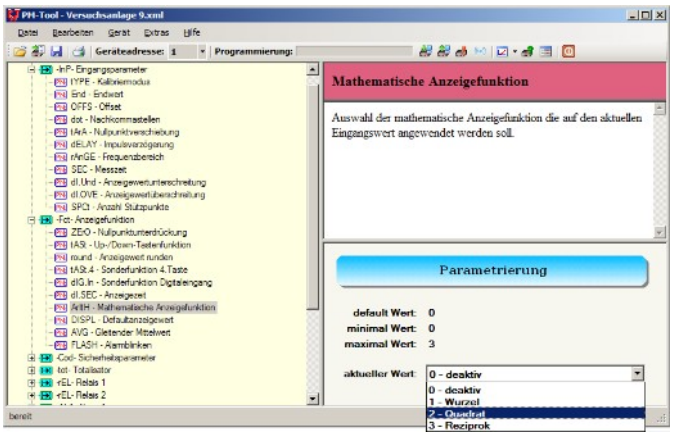
Please state the advertisement label in plain text.

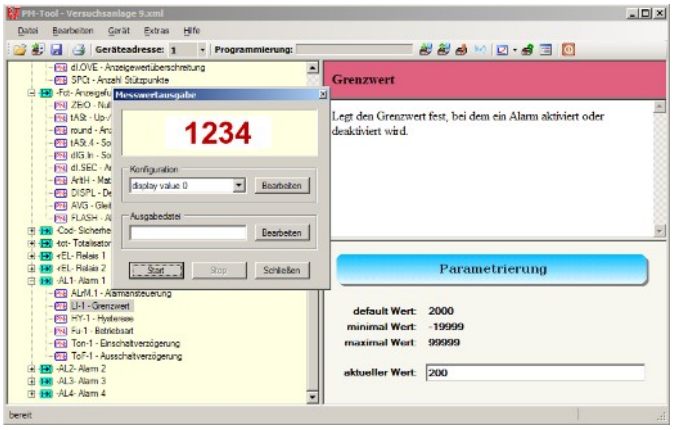
Please note:

With 48 x 96 mm version and 230 VAC supply (types AZ20.4.x.1....) not all combinations of output signals and relay outputs are possible due to the increased space requirements of the power supply unit.
For example, the combination of 1 x analogue output and encoder supply is possible, but a second analogue output is no longer possible.

Accessories: Programming Software

With the programming software, all device parameters can be read out, adapted and transferred back to the device. The PC is connected to the AZ20 via a USB cable, which is also available as an accessory. The complete parameter set can be saved in XML format and read in again if required. Thus, an AZ20 can be quickly converted for various projects and measurement tasks by simply reading in another parameter set.
In addition to the display and scaling settings, mathematical functions can also be applied to the measured value and – depending on the instrument version -the limit values for the alarm and relay outputs can be set. Furthermore, the measured values can also be recorded and saved as a file on the PC
A characteristic curve with up to 30 calibration points can be programmed, especially for adaption to different sensors.





The software is currently only available for Windows©-operating systems.

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